



High Performance 1/16 DIN size Controller

A 1/16 DIN unit (48x48mm) has been added to the FB series high performance and highly reliable controllers.

High performance control is achieved in a small installation space.

* Some functions on FB100 may be limited compared to FB900/400

RoHS compliant Reinforced Insulation





NEW

(Actual size)

High performance

High accuracy : 0.1%

Selectable sampling time:

50msec (Fast response) /100ms (Standard) /250msec (High resolution) Brilliant II PID Control

Selectable PID control algorithm

PV Derivative PID: suitable for fixed setpoint control (Factory setting) Deviation derivative PID: suitable for ramp control using ramp-to-setpoint function and cascade control

Ramp-to-setpoint/Output change rate limiter Advanced Heat/Cool PID algorithm with Undershoot Suppression

• Numerous inputs and outputs (Released soon) ogging tool **Universal input** Up to 2 points Up to 3 points Thermocouple • RTD DC voltage • DC curre Communication Digital output Up to 5 points **Digital** input Analog 100.00 Remote setting input Heat control Cool control Up to 2 points CT input Heat/Cool control Position proportioning User-friendly Keys and Display One-touch Operation on Mode Selection, Memory Easv-to-read 5 Digit LED Display Area Selection and Monitor AUTO/MAN LOC/REM Bar Graph display (10 LED segments) · Control output value Setting value (SV) Measured value (MV) • CT1/CT2 input Deviation between Elastomer key tops SV and PV

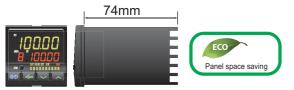
Easy maintenance

The internal assembly of the FB100 can be removed from the front.



Panel space saving: 74mm depth

The FB100 has very short depth as a 1/16 DIN size controller. The FB100 was designed with a mounting bracket that allows close horizontal mounting of as many as six units.



Reinforced Insulation

Reinforced insulation retains its insulating ability even when basic insulation breaks down. The power circuits in our instruments are designed with reinforced insulation and will save costs by eliminating the need for additional safety measures to prevent break-down shock.

<Requirements for electrical equipment according to safety standards>

The safety standards on electrical equipment (JISC 1010-1 and IEC 61010-1) require that the secondary side of the equipment which may be touched by the operator should be double insulated or reinforcement insulated* from high voltage that would result in electric shock.

Insulation safeguarding personnel from electric shock which is equal to double insulation or higher is called "reinforced insulation".

Inter-controller Communication

Inter-controller communication achieves more precise cascade control and ratio control by sending data via digital communication while conventional cascade controllers send data to slave controllers by analog signal with less resolution.

CH B

Reduce power

consumption

CHC

CH D

Reduces waste of power in the waiting channels once temperature rise has been completed.

Group 1

CHA

Auto-temperature-rise with Learning Function

Auto-temperature-rise with learning function achieves temperature uniformity at ramp-up without partial thermal expansion even when using multiple FB100 controllers

Time

All ÇH

npera comp

-Time

All ÇH

mperature completi

Up to 32 controllers with 16 groups can be configured.
 Auto-temperature-rise function is not available with position proportional PID control type.

Start

With Auto-temperature-rise

Temperature Ratio Setting

If the master controller changes the control set value, the slave controllers will also change the set values by following preset ratios to the master.

· Up to 32 controllers with 16 groups can be configured.



Cascade Control

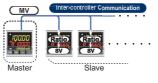
Without Auto-temperature-rise

CH A wait CH B wait CH C wait

CHA В

Start

It is effective when a thermal time-delay exists between the heat source and a control point. A maximum of 31 slave controllers can be connected to one master controller.



When RUN/STOP mode is changed on one controller in a group, the mode of all the other controllers in the same group will be also automatically changed.

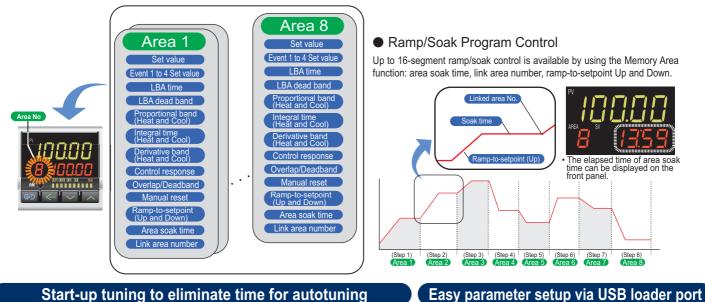




(Note) Time lag among controllers caused by inter-controller communication is Max.70ms x number of controllers connected. Please consider the time lag of inter-controller communication for high-speed process control in which process changes rapidly.

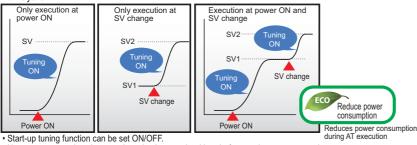
Recipe (Multi-memory Area) Function

The FB100 has Multi-memory Area function which stores up to 8 sets of control parameters. Parameters in a memory area can be changed at one time by selecting the memory area number through key operation, DI, or communication.



Start-up tuning to eliminate time for autotuning

Start-up tuning eliminates time required for conventional autotuning as it calculates optimum PID values by temperature characteristics at start up. It is useful in applications which require a long time for conventional autotuning. The timing of activation of start-up tuning can be selected from at power-up, at setpoint change, and at power-up/setpoint change. It is also settable to Only-once or always-ON



- · Heater power needs to be turned on simultaneously with or before turning on power to the temperature controller.
- · Start-up tuning (ST) is when the temperature differential of the measured value (PV) and set value (SV) is at least twice the proportional band at the start of start-up tuning (ST).
- · If start-up tuning does not calculate suitable PID values due to characteristics of application, use Autotuning function
- · Start-up tuning function is not available with position proportional PID control type.

are easily copied to other controllers. USB communication converte COM-K Model code COM-K-1 (With loader communication cable) (Port) COM-K-N (Without loader communication cable) USB PORT oader communication USB COM-K Cable length : 1.5m Cable length : 1m (COM-K standard accessory)

The FB series has a standard loader port to connect to a PC USB

Using Win-UCI software on the PC, parameter settings can be easily saved on the PC in CSV format, and the same parameter settings

port via COM-K: USB communication converter.

- The loader port is only for parameter setup.
 The power to COM-K is supplied from the PC via
- the USB port so no power supply is necessary

Specifications

Input						
Input	 Universal input Temperature, Current, Low voltage input group Thermocouple : K, J, E, T, R, S, B, N (JIS/IEC) PLII (NBS), W5Re/W26Re (ASTM) U, L (DIN) RTD : Pt100 (JIS/IEC), JPt100 (JIS) 3-wire system Low voltage (Input impedance : More than 1MΩ) 0 to 1V DC, 0 to 100mV, 0 to 10mV DC -100 to +100mV DC, -10 to +10mV DC Current (Input impedance : 50Ω) 4 to 20mA, 0 to 20mA b) High voltage input group High voltage (Input impedance : 1MΩ) -1 to +1V DC, 0 to 5V DC, 1 to 5V DC, 0 to 10V DC 					
Sampling time	(Use dip switch to change input group.) 0.1sec					
earriping arrie	0.05sec/0.25sec is selectable.					
Influence of external resistance	$0.2\mu V/\Omega$ (Thermocouple input)					
Influence of lead resistance	0.01% of reading/Ω (RTD input) • Maximum 10Ω per wire					
Input break action	Thermocouple input : Up-scale/Down-scale (Selectable) RTD input : Up-scale Low voltage input : Up-scale/Down-scale (Selectable) Current input : Value around 0mA High voltage input : Value around 0V					
Input short action Down-scale (RTD input)						
Input digital filter	0.1 to 100.0 sec. (OFF when 0 is set.)					
PV bias	-span to +span					
PV ratio	0.500 to 1.500					
Square root extraction	PV = √(Input value x PV ratio + PV bias) Low level cut off : 0.00 to 25.00% of span					

Control

Control method	a) Brilliant II PID control				
	Direct action/Reverse action is selectable				
	b) Brilliant II PID control (Heat/Cool type)				
	c) Position proportioning control without feedback resistance				
	 a), b), c) is selectable 				
Autotuning	a) For PID control (Direct action/Reverse action)				
	b) For Heat/Cool PID control (For extruder, air cooling)				
	c) For Heat/Cool PID control (For extruder, water cooling)				
	d) For Heat/Cool PID control				
Start-up tuning	The condition to activate Start-up tuning is selectable among a) to g).				
	a) At power-on, one-time tuning				
	 b) At SV change, one-time tuning 				
	c) At power-on and SV change, one-time tuning				
	d) At power-on, always on				
	e) At SV change, always on				
	 f) At power-on and SV change, always on 				
	g) Function off				
	(Not available for Heat/Cool PID control type)				
Setting range	a) Proportional band :				
	Temperature input : 0 to input span (°C,°F)				
	Voltage/Current input : 0.0 to 1000.0% of input span				
	(ON/OFF control when P = 0)				
	Differential gap at ON/OFF control (High/Low individual setting) :				
	Temperature input : 0 to input span (°C,°F)				
	Voltage/Current input : 0.0 to 10.0% of input span				
	b) Integral time : 0 to 3600 sec or 0.0 to 1999.9 sec (selectable)				
	(PD control when $I = 0$)				
	c) Derivative time : 0 to 3600 sec or 0.0 to 1999.9 sec (selectable)				
	(PI control when $D = 0$)				
	 d) Cool side proportional band : Temperature input : 1(0.1, 0.01) to input span (°C,°F) 				
	Voltage/Current input : 0.1 to 1000.0% of input span				
	e) Cool side Integral time :				
	0 to 3600 sec or 0.0 to 1999.9 sec (selectable)				
	(PD control when I = 0)				
	f) Cool side Derivative time :				
	0 to 3600 sec or 0.0 to 1999.9 sec (selectable)				
	(PI control when I = 0)				
	g) Overlap/Deadband				
	Temperature input : -span to +span (°C,°F)				
	Voltage/Current input : -100.0 to +100.0% of input span				
	h) Control response : Slow, Medium, Fast				
	i) Ramp-to-setpoint				
	0 to span per Time				
	(Time is settable between 1 and 3600 sec)				
	Up/Down individual setting				
	j) Output limiter : -5.0 to +105.0% (High/Low individual setting)				
	k) Output change rate limiter : 0.0 to 100.0%/sec				
	(Up/Down individual setting)				
	I) Proportional cycle time : 0.1 to 100.0 sec				
	m) Cool side proportional cycle time : 0.1 to 100.0 sec				
	n) Manual reset : -100.0 to +100.0%				
	 Output at Control Stop mode : -5.0 to +105.0% 				

(Heat side/Cool side individual setting)

Position Proportional Control

Motor time	5 to 1000 sec
Integral output limiter	OFF, 0.1 to 250.0% of motor time
Neutral zone	0.1 to 10.0%
Differential gap	0.1 to 5.0%
Output at Control	Selectable from the following :
Stop mode	a) Close : Output off, Open : Output off
	b) Close : Output on, Open : Output off
	c) Close : Output off, Open : Output on

Performance

Measuring accuracy	a) Thermocouple					
accuracy	Type : K, J, T, E, PLII, U, L					
	Less than -100°C (-148°F) : ±1.0°C (±1.8°F)					
	-100 to +500°C (-148 to 932°F) : ±0.5°C (±0.9°F)					
	More than 500°C (932°F) : ±(0.1% of reading + 1 digit)					
	Type : N, S, R, W5Re/W26Re					
	Less than 0°C (32°F) : ±2.0°C (±3.6°F)					
	0 to 1000°C (32 to 1832°F) : ±1.0°C (±1.8°F)					
	More than 1000°C (1832°F): ±(0.1% of reading + 1 digit)					
	Type B					
	Less than 400°C (752°F) : ±70.0°C (±126°F)					
	400 to 1000°C (752 to 1832°F) : ±1.0°C (±1.8°F)					
	More than 1000°C (1832°F): $\pm (0.1\% \text{ of reading} + 1 \text{ digit})$					
	Cold junction temperature compensation error					
	±1.0°C (1.8°F) [Between 5 and 40°C (41 and 104°F)]					
	$\pm 1.5^{\circ}$ C (2.7°F) [Between -10 and 5°C (16 and 41°F), and					
	40 and 50°C (104 and 122°F)]					
	b) RTD					
	Less than 200°C (392°F) : ±0.2°C (±0.4°F)					
	More than 200°C (392° F) : ±(0.1% of reading + 1 digit)					
	c) DC voltage and DC current					
<u></u>	±(0.1% of span)					
Close horizontal mounting error	±1.5°C (2.7°F)					
Insulation	More than 20M Ω (500V DC) between measured terminals and ground					
resistance	More than 20M Ω (500V DC) between power terminals and ground					
	More than 20M Ω (500V DC) between measured and power terminals					
Dielectric	1500V AC for one minute between measured terminals and ground					
voltage	1500V AC for one minute between power terminals and ground					
	2300V AC for one minute between measured and power terminals					

Output

Number of outputs	Up to 2 points (OUT1, OUT2)					
Output function	Control output, HBA output, FAIL output					
 See output allocation table (page 7) 						
Output signal	a) Relay contact output, Form a cor	ntact				
	250V AC 3A (Resistive load)					
	 Electric life : 100,000 cycles or 	more				
	b) Voltage pulse output, 0/12V DC					
	(Load resistance : More than 600	0Ω)				
	c) Current output, 4 to 20mA DC, 0	to 20mA DC				
(Load resistance : Less than 600Ω) d) Continuous voltage output,						
(Load resistance : More than $1k\Omega$)						
	e) SSR (Triac) output, Rated current : 0.5A					
f) Open collector output (Sink type)						
	Load voltage : Less than 30V DC					
	Load current : Less than 100m	۱A				
	maximum load current)					
	5					
Digital Ou	itput (DO)	(Standard)				
		(Ctandard)				

Number of outputs	s Up to 2 points (DO 1 to 2)
Output function	Event output, Heater break alarm (HBA), FAIL
Output signal	Relay contact output, Form a contact
	250V AC 1A (Resistive load)

Multi-Memory Area (recipe)

Number of areas 8 areas (recipes)					
Stored	Set value (SV), Event set values 1 to 4, LBA time, LBA dead band,				
parameters	Proportional band, Integral time, Derivative time,				
	Cool side proportional band, Cool side integral time				
	Cool side derivative time, Overlap/Deadband, Manual reset				
	Control response parameter, Ramp-to-setpoint (Up/Down)				
	Soak time, Linking area number				
Soak time	0 min 00 sec to 199 min 59 sec or				
	0 hr 0 min to 99 hr 59 min				
	(selectable)				
Linking area number	OFF, 1 to 8				

Specifications

Event (Alarm)						
	(Stalidard)						
Number of events Event type	Up to 4 points Process high, Process low, Deviation high, Deviation low Deviation high/low, Band, Set value high, Set value low, MV value high, MV value low, Cool side MV value high, Cool side MV value low, FBR value high, FBR value low, LBA (Control loop break alarm)						
LBA is assignable to event 4.							
Setting range a) Deviation alarm Event set value : -input span to +input span Event action differential gap : 0 to input span b) Process alarm/Set value alarm Event set value : Same as input range							
	Event action differential gap : 0 to input span c) MV alarm, FBR alarm -5.0 to +105.0%						
	d) LBA LBA time : 0 to 7200 sec (LBA is OFF when 0 is set.) Dead band : 0 to input span						
	Assignable to digital output (DO 1 to 2) or Output 2 (OUT2) • See output allocation table (page 7)						
Other functions	 a) Hold/Re-hold action (Valid for deviation/band/process alarm only) Hold action is activated at Power-up and STOP to RUN. Re-hold action is activated at Power-up, STOP to RUN and the control set value change. b) Event action is configurable in case of input abnormality. 						
	c) Energized/de-energized action is configurable.						
	d) Delay timer : 0.0 to 600.0 sece) Interlock (latch) function is configurable.						
Heater	Break Alarm (HBA) (Optional)						
	s 2 points (1 point per CT input)						
CT Type and	CTL-6-P-N : 0 to 30A						
input range Display range	CTL-12-S56-10L-N : 0 to 100A 0.0 to 100.0A						
	±(5% of input value + 1 digit) or 2A (whichever is larger)						
	Assignable to output 2 or digital output (DO 1 to 2) • See output allocation table (page 7)						
Digital Ir	nput (DI) _(Optional)						
Number of inputs	S Up to 5 points (DI 1 to 5)						
Input method Function	Non-voltage contact input Memory area selection (Area set/No area set is selectable) RUN/STOP, Remote/Local, Auto/Manual, Alarm interlock reset						
	 Selectable See digital input allocation table (page 7) 						
Remote S	etpoint Input (Optional)						
Input	a) Low voltage group 0 to 1V DC, 0 to 100mV DC, 0 to 10mV DC						
	b) High voltage group 0 to 5V DC, 1 to 5V DC, 0 to 10V DC						
	 c) Current group 4 to 20mA DC, 0 to 20mA DC • Universal input 						
	Not isolated from measured input						

 • Not isolated from measured input

 Sampling time
 0.1 sec (with measuring input sampling time of 0.05 sec)

 0.2 sec (with measuring input sampling time of 0.1 sec)

 0.5 sec (with measuring input sampling time of 0.25 sec)

 Accuracy
 ±0.1% of span

Analog Retransmission Output (AO)

Number of outputs	3 1 point
Output type	Measured value (PV), Set value (SV)
	Manipulated value (MV), Deviation (between PV and SV)
	Selectable
Output signal	4 to 20mA DC, 0 to 20mA DC
	(Load resistance : Less than 600Ω)
	0 to 1V DC, 0 to 5V DC, 1 to 5V DC, 0 to 10V DC
	(Load resistance : More than $1k\Omega$)
Resolution	Approx. 1/4000
Output accuracy	±0.1% of span

(Optional)

Resistance value Standard : 100 to $10k\Omega$ (factory default 135Ω) Sampling time 0.1 sec (with measuring input sampling time of 0.05 sec) 0.2 sec (with measuring input sampling time of 0.1 sec) 0.5 sec (with measuring input sampling time of 0.25 sec) Communications (Optional) Communication COM1 : RS-485 method Communication 2400bps, 4800bps, 9600bps, 19200bps, 38400bps speed a) ANSI X3.28 sub-category 2.5A4 (RKC standard) Protocol b) MODBUS-RTU Bit format a) RKC standard protocol Start bit : 1 Data bit : 7 or 8 Parity bit : 1 (odd or even) or none Stop bit : 1 or 2 b) MODBUS protocol Start bit : 1 Data bit : 8 (binary or byte data) Parity bit : 1 (odd or even) or none Stop bit : 1 or 2 Maximum 32 units (Including host) connection Inter-controller Communication (Optional)

(Optional)

Feedback Resistance (FBR) Input

Function : Auto-temperature-rise, Cascade control, Temperature ratio setting, Group STOP/RUN

Loader communication

Protocol	ANSI X3.28 sub-category 2.5A4 (RKC standard)
Communication speed	38400bps
Bit format	Start bit : 1, Data bit : 8, Parity bit : none, Stop bit : 1
Maximum connection	1 unit (Address : 0)

(Standard)

Waterproof/Dustproof

NEMA4X, IP66

Waterproof/Dustproof protection only effective from the front in panel mounted installation.

General Specifications

Supply voltage	a) 90 to 264V AC (50/60Hz, Selectable)
	Rating : 100 to 240V AC
	b) 24V AC ±10% (50/60Hz, Selectable)
	Rating : 24V AC
	c) 24V DC ±10%
	Rating : 24V DC
Power consumption	a) 100 to 240V AC type
	5.4VA (240V), 8.1VA (100V)
	b) 24V AC type
	5.3VA
	c) 24V DC type
	142mA
Rush current	Less than 12A
Power failure	A power failure of 20m sec or less will not
	affect the control action. If power failure of more
	than 20m sec occurs, controller will restart with the state
	of HOT start 1, HOT start 2 or COLD start (selectable)
Memory backup	Backed up by non-volatile memory (FRAM)
	 Data retaining period : Approx. 10 years
	• Number of writing : Approx. 1,000,000,000,000 times.
	(Depending on storage and operating conditions.)
Ambient temperature	-10 to +50°C (14 to 122°F)
Ambient humidity	5 to 95% RH (Non condensing)
	 Absolute humidity : MAX.W.C 29g/m³ dry air at 101.3kPa
Weight	Approx. 150g
Operating	Free from corrosive and flammable gas and dust.
environment	Free from external noise, vibration, shock and exposure
	to direct sunlight.
Compliance with Standards	CE Mark, UL, C-UL, C-Tick mark

Model and Suffix Code

		Model and Suffix Code	;					Accessories (Sold separately)
Specifications		Hardware c ① ② ③		-	-	Quic code ⑦	k start 1 ⑧ ⑨	Current transformer for
		(48 x 48mm 1/16 DIN size) FB100 -	· _ /			-0[ĬĬ.	heater break alarm (HBA)
	Output 1 (OUT 1)	Relay contact output M Voltage pulse output (0/12V DC) V DC mA, V See Output Code Table Triac output T Open collector output D						Model code (Unit : mm) CTL-6-P-N [0 to 30A] CTL-12-S56-10L-N (0 to 100A) CTL-6-P-N CTL-6-P-N
	*1 Output 2 OUT 2)	Not supplied N Relay contact output M Voltage pulse output (0/12V DC) V DC mA, V See Output Code Table Triac output T Open collector output D						Approx.130 25 145 ↓5.8 ↓5.8 CTL-12-S56-10L-N
3 Pov	wer Supply	24V AC/DC 3 100 to 240V AC 4						Approx.10040
	otional	Not supplied Digital input 5 points Digital input 2 points + Remote setpoint input Digital input 2 points + Feedback resistance input Digital input 2 points + CT input 2 points Digital input 3 points + Communication 1 point + CT input 1 point Communication 2 points Communication 1 point + CT input 2 points Digital input 1 point + Remote setpoint input + Analog retransmission output 0 to 1V DC Digital input 1 point + Remote setpoint input + Analog retransmission output 0 to 5V DC Digital input 1 point + Remote setpoint input + Analog retransmission output 0 to 5V DC Digital input 1 point + Remote setpoint input + Analog retransmission output 0 to 20mA Digital input 1 point + Remote setpoint input + Analog retransmission output 0 to 20mA Digital input 1 point + Remote setpoint input + Analog retransmission output 0 to 20mA Digital input 1 point + Remote setpoint input + Analog retransmission output 4 to 20mA	N A B C D E F G H 3 3 4 5 6 7 8					• Terminal Cover
5 Cas	se color	White case Black case		N A				Model Code :
6 Qui	ick start de	No quick start code (Default setting) Specify quick start code 1 Specify quick start code 1 and 2 (See page 11)			N 1 2			KCA100-517 ● Front Cover
start co		No quick start code PID control with AT (Reverse action) ♦ PID control with AT (Direct action) Heat/Cool PID control with AT Heat/Cool PID control with AT for extruder (Air cooling type) Heat/Cool PID control with AT for extruder (Water cooling type) Position proportional PID control without FBR			-	No Code F D G A W Z	e	
80	Input and range				N	o Code	Model Code : KRB100-36A	
O	rument version	Version symbol					/Y	J

Default setting
Digital output (DO1, DO2) : Standard function
*1 : When Heat Control or Cool Control is selected, output 2 is available for Event Output, HBA Output and FAIL Output. See Output Allocation Table (page 7).
*2 :See Digital Input (DI) Allocation Table (page 7).
*3 :When HBA (heater break alarm) is used , select the "CT input" from the model code.

(Output Code Table										
	Output Type	Code	Output Type	Code							
	0 to 5V DC	4	0 to 20mA DC	7							
	0 to 10V DC	5	4 to 20mA DC	8							
	1 to 5V DC	6									

Input Range Code Table

Thermocouple

Thermocouple											RTD					
Input	nput Code Range Input Code Range						Input	Code	e l	Rang	ge	Input	Code	F	Range	
	K 35	-200.0 to +400.0°C		J C7	-200.0 to	+700.0°F	PLII	A 02		0 to	1390°C		D 34		0 to+100.00°C	
	K 40	-200.0 to +800.0°C			J C6	-328.0 to -	+1200.0°F	(NBS)	AA		0 to	2534°F		D 35	-200.0	0 to +850.0°C
	K 09	0.0 to 400.0°C		J B6	0.0 to	800.0°F	W5Re/W26Re			0 to	2300°C	Pt100	D 21	-200.0	0 to +200.0°C	
	K ¦ 10	0.0 to 800.0°C	J	J	J B9	-328 to	+2192°F	(ASTM)	W A		0 to	4200°F		D C8		9 to +199.99°F
	K ¦41	♦ -200 to +1372°C		J ¦A1	0 to	800°F	U	U ¦ 04	0.	0 to	600.0°C		D C9	-328.0	0 to +1562.0°F	
K	K 02	0 to 400°C		J ¦A2	0 to	1600°F	(DIN)	UB	2 32.	0 to	1112.0°F		D D1	-200.0		
	K ¦04	0 to 800°C	т	T ¦ 19	-200.0 to	+400.0°C	L	L ¦ 04	0.	0 to	900.0°C		P ¦29	-100.00	0 to+100.00°C	
	K ¦C6	-250.0 to +800.0°F	1	T C2	-328.0 to	+752.0°F	(DIN)	LA	32.	.0 to 1652.	1652.0°F		P ¦30		0 to +640.0°C	
	K ¦C4	-328.0 to +400.0°F	S	S \ 06	-50 to	+1768°C						JPt100	P ¦C8		9 to +199.99°F	
	K¦A4	0.0 to 800.0°F		S ¦A7	-58 to	+3214°F						P ¦C	P ¦C9	-328.0) to +1184.0°F	
	K ¦C5	-328 to +2502°F		R ¦ 07	-50 to	+1768℃							P ¦D1	-200.0) to +200.0°F	
	K ¦A1	0 to 800°F	R	R ¦ A7	-58 to	+3214°F	DC Current · voltage									
	K ¦A2	0 to 1600°F		E ¦ 21	-200.0 to	+700.0℃				Ŭ					_	
	J ¦ 27	-200.0 to +400.0°C	–	E ¦06	-200 to	+1000℃	Inpu		Code	R	ange	Inpu		Code	Range	
	J ¦ 32	-200.0 to +800.0°C	E	E¦A9	-328.0 to -	+1292.0°F	0 to 10r		1 01			20mA*1	7 01			
	J ¦08	0.0 to 400.0°C		E ¦B1	-328 to	+1832°F	0 to 100	DmV	2 01				20mA*1	8 01	0.0 to 100.0%	
J	J ¦09	0.0 to 800.0°C	В	B ¦ 03	0 to	1800°C	0 to 1V			0.0 t	to 100.0%	-100 to +		9 01	0.0 10 100.0%	
	J ¦ 15	-200 to +1200°C	D	B B2	0 to	3272°F	0 to 5V		4 01			-1 to +1V 9 02				
	J ¦02	0 to 400℃	N	N 02	0 to	1300°C	0 to 10	/	5 01			-10 to 10mV 9 03				
	J ¦04	0 to 800℃	IN	N A7	0 to	2372°F	1 to 5V		6¦01			*1 : Shunt resistor is not required for				
Default setting current input.																

Default setting

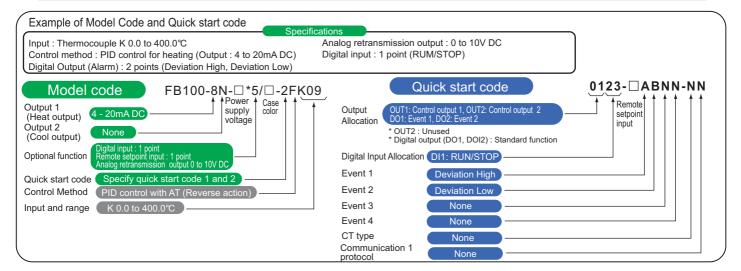
Quick start code

 Quick start code tells the factory to ship with each parameter preset to the values detailed as specified by the customer. Quick start code is not necessarily specified when ordering, unless the preset is requested. These parameters are software selectable items and can be re-programmed in the field via the manual.

ç	Specifications	Qui	ck start code) (<u>4</u>)]-[]	5		8 (9			ent Code	Table	
	Output allocation	(See output allo	cation table)								È	ammable)		
	Digital input allocation	· · · ·									Code	Ev	ent type	
<u> </u>	<u> </u>	No Remote set	point input signa	I N							Α	Deviation High	1	
		0 to 10mV DC	1 3	1							В	Deviation Low		
		0 to 100mV DC		2							C	Deviation High	/Low	
3	Remote setpoint	0 to 1V DC		3	-						D	Band		
Ŭ	input signal	0 to 5V DC		4							E	Deviation High	with Alarm H	old
		0 to 10V DC		5							F	Deviation Low		
		1 to 5V DC		6							G	Deviation High	/I ow with Ala	rm Hold
		0 to 20mA DC		7							H	Process High		
		4 to 20mA DC		8	_						J	Process Low		
4	Event 1 type	No event 1			N						ĸ	Process High	with Alarm Ho	Id
		See event type	code table									Process Low v		
5	Event 2 type	No event 2				N					Q	Deviation High		
<u> </u>		See event type	code table)								R	Deviation Low		
	Event 3 type	No event 3					Ν				T	Deviation High/I		
6		See event type	e code table								v	Set value High		
	Event 4 type	No event 4					N				Ŵ	Set value Low		
7		(See event type	code table					-			1	MV value High	1	
U			eak alarm (LBA)	1			5	-			2	MV value Low		
		No CT1 and CT						N			3	Cool side MV	value High	
		CT1 : CTL-6-P-		: No use				P			4	Cool side MV		
8	CT type		556-10L-N, CT2					S						
		CT1 : CTL-6-P-	N, CT2	: CTL-6-P-N				Т		• Dofau	It cottin		ick start cor	lo is specified
		CT1 : CTL-12-S56-10L-N, CT2 : CTL-12-S56-10L-N								Default setting when no quick start code is specified. CT type : CTL-6-P-N				
		No communica							Ν			ion 2 :ANSI/R	KC standar	1 protocol
(9)	Communication 1	ANSI/RKC star							1					communication.
9	Communication	MODBUS prote							2	Comm	iunicalic			ommunication.
		Inter-controller	protocol					1	Α					
<u></u>	Itput Allocation	Table				Jiai	alinn		N /	Allocatio	n Tabl			
Ju	itput Allocation		nyii		מנ (ש	1) /	hillatio		·	•	Default setting			
Co	ode Output 1	Output 2	Digital Output 1	Digital Output 2		ode	DI	1		DI 2	DI 3	DI4	DI 5	Selectable
	(OUT 1)	(OÚT 2)	(DO 1)	(DO 2)		Jue	DI	1			013	DI4	DIS	optional Code
0	1 Control output 1	Control output 2	Event 1	Event 2	0	11					Unus	ed		
0	2 Control output 1	Control output 2	Event 1	Event 4	0)2	Mer	nory a	rea	a selection	(1 to 8)	Area set	RUN/STOP	
0	3 Control output 1	Control output 2	Event 1	HBA	0)3	Mer	nory a	rea	a selection	(1 to 8)	Area set		
_		· · · ·									(1

		(0012)	(DO 1)	(DO 2)							optional Code		
01 🔶	Control output 1	Control output 2	output 2 Event 1 Event 2 01♦				Unused						
02	Control output 1	Control output 2	Event 1	Event 4	02	Memory	area selectio	on (1 to 8)	Area set	RUN/STOP			
03	Control output 1	Control output 2	Event 1	HBA	03	Memory	area selectio	on (1 to 8)	Area set				
04	Control output 1	Control output 2	Event 1	FAIL (De-energized)	04	Memory	area selectio	on (1 to 8)		AUTO/MANUAL			
05	Control output 1	Control output 2	Event 4	HBA	05	Memory	area selectio	on (1 to 8)	Area set	Alarm interlock reset			
06	Control output 1	Control output 2	Event 4	FAIL (De-energized)	06	Memory	area selectio	on (1 to 8)	RUN/STOP		A		
07	Control output 1	Control output 2	HBA	FAIL (De-energized)	07		area selectio	/		AUTO/MANUAL			
08	Control output 1	HBA	Event 1	Event 2	08		area selectio		RUN/STOP	Alarm interlock reset			
09	Control output 1	HBA	Event 1	Event 4	09	Memory	area selectio	on (1 to 8)		AUTO/MANUAL			
10	Control output 1	HBA	Event 1	FAIL (De-energized)	10	Memory	area selectio	on (1 to 8)		Alarm interlock			
11	Control output 1	HBA	Event 4	FAIL (De-energized)	11		area selectio	<u> </u>	AUTO/MANUAL	Alarm interlock			
12	Control output 1	FAIL (De-energized)	Event 1	Event 2	12		area selectio						
13	Control output 1	FAIL (De-energized)	Event 1	Event 4	13		REMOTE/LOCAL						
14	Control output 1	Event 1	Event 2	Event 3	14		REMOTE/LOCAL	Alarm interlock			A, E		
15	Control output 1	Event 4	Event 1	Event 2	15		AUTO/MANUAL						
• Ener	aized/De-eneraize	ed is configurable e	except for the FAIL	output.				Alarm interlock					
	tory default setting				17		REMOTE/LOCAL						
(Cautio	on)				18		AUTO/MANUAL						
 Inva 	lid for a non-existi	ng output/input fun	ction.		19	RUN/STOP	Alarm interlock reset			·	A, B, C, D, E		
 Whe 	n used as heating	/cooling control/po	sition proportionin	g		REMOTE/LOCAL	AUTO/MANUAL				A, D, C, D, E		
	rol, select any cod			21	REMOTE/LOCAL								
		can be done during	g cascade control	22	AUTO/MANUAL	Alarm interlock							
by in	ter-controller com	munication.			23	RUN/STOP							
					24	REMOTE/LOCAL					A, B, C, D, E, F		
					25	AUTO/MANUAL					3, 4, 5, 6, 7, 8		

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Alarm interlock

External Dimensions

