

SRZ

Module type
Process/Temperature Controller

SRZ
High-Performance



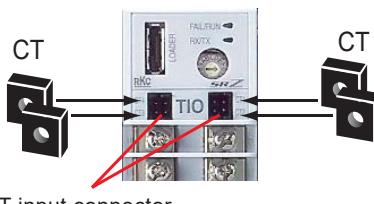
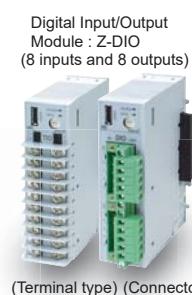
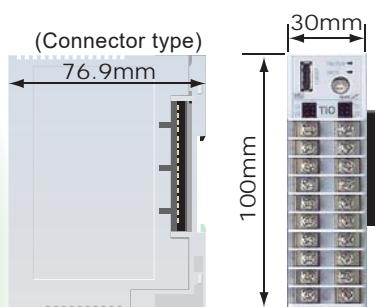
CE cUL us RCM
CE,UL,c-UL,RCM

RKC **RKC INSTRUMENT INC.**

4CH temperature controller packed in one compact module

● Compact

Width 30mm, depth 85mm (connector type : 76.9mm) compact design with 4ch control type.

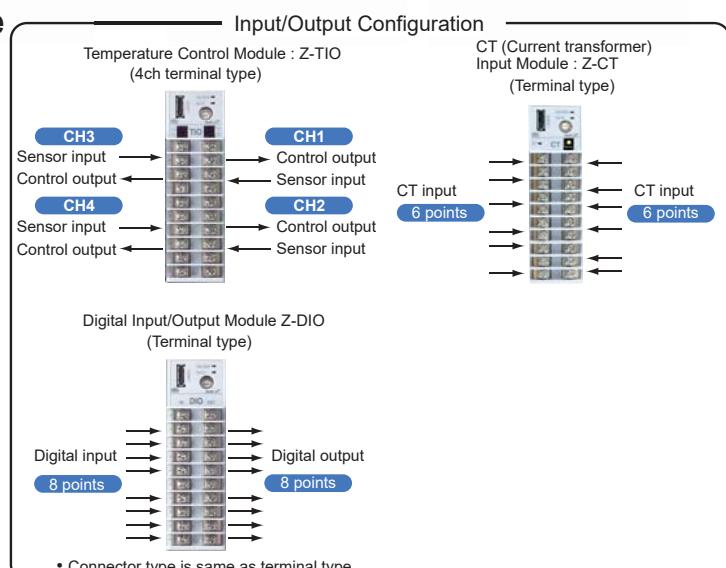
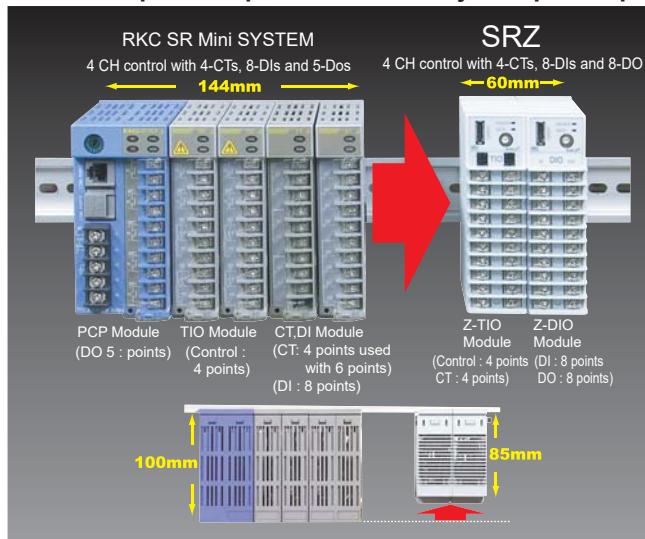


CT input connector

Communication Extension Module : Z-COM
(High-speed communication gateway)



● Ultra compact - requires substantially less panel space

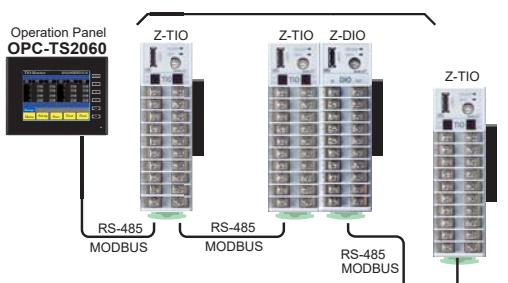


Flexible temperature control system configuration

● Distributed installation

Modules can be remotely distributed by connecting them via RS-485 communication. Up to 16 Z-TIO (64 CH) and 16 Z-DIO (128 DI/DOs) modules can be connected to one serial communication line by distributed installation.

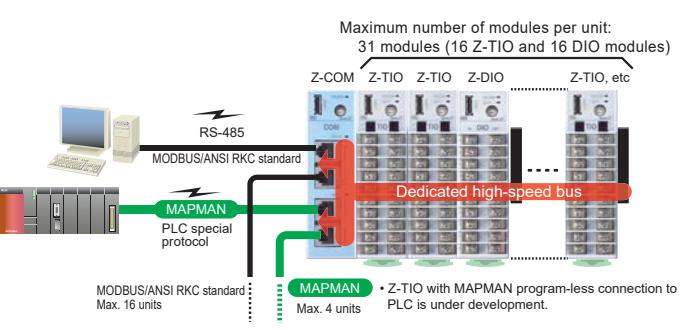
The maximum number of modules connected by distributed installation is 31 modules.



● High-speed communication with large systems, Program-less connection to PLCs

Z-COM module can manage data from connected control modules via high-speed bus connection. MAPMAN program-less connection to PLC is also available.

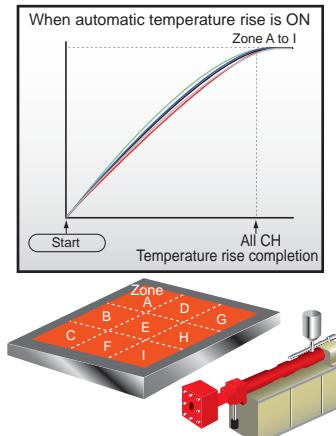
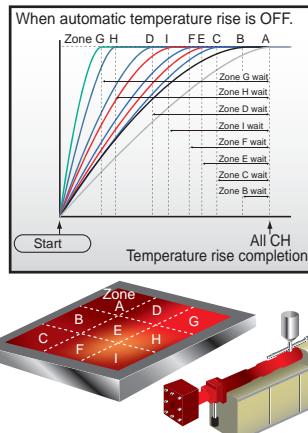
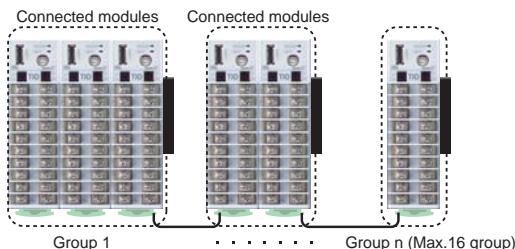
Program-less connectable PLCs: Mitsubishi Electric MELSEC Series



Advanced functions enhance multi-loop control

● Temperature uniformity at ramp-up (Auto-temperature rise function)

The Auto-temperature rise function controls the rate of temperature rise uniformly across all the channels in a specified group. The SRZ system has the ability to have multiple groups within each system. This uniform controlled temperature rise will suppress local overheating and mechanical distortion in the tools, contributing to higher product quality.

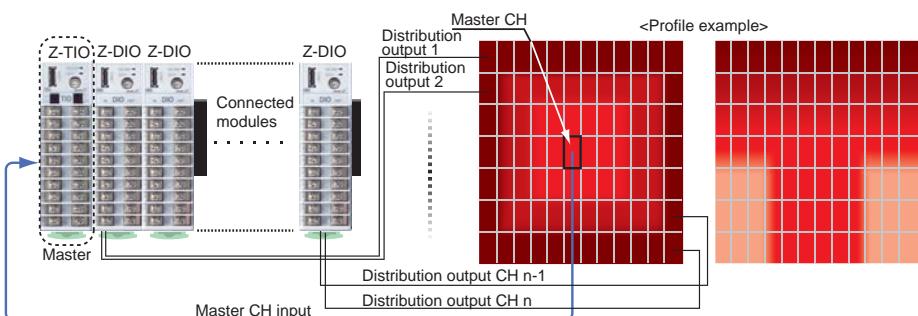


● Multi-loop profile control (Output ratio distribution function)

This function enables one master loop to distribute its output value to multiple outputs of Z-DIO modules. Bias and ratio can be set for each output independently.

A maximum of 187 distribution outputs from one control loop is possible when Z-DIOs and Z-TIOs are used for output ratio distribution.

- Output ratio distribution function works via back plane connected modules.
- Distribution output from DIO module becomes open collector output or relay contact output.

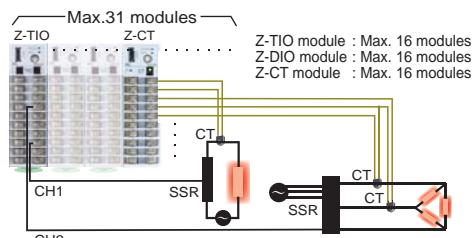


● Automatic SV setting on heater break alarm and heater over current alarm

Set values of Heater break alarm (HBA) and heater over current alarm are automatically set by pressing a front-mounted push button when a heater is on.

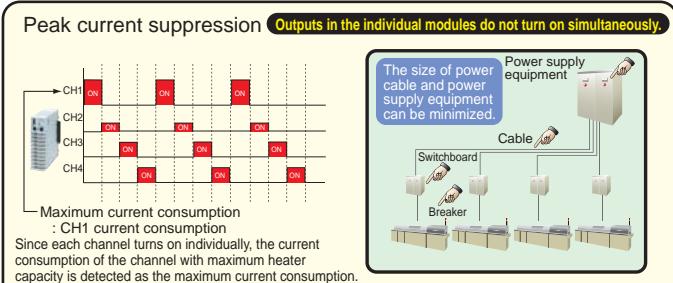
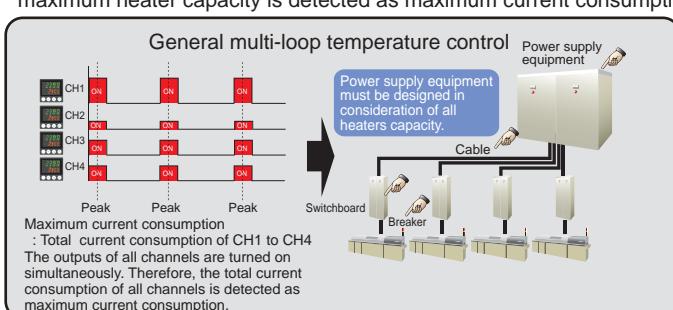
This function is also available for three-phase heater break alarm.

- HBA function of Z-CT module is designed only for time proportional control (On/Off output.) Phase control (continuous output) is not available.
- The CT input monitor value indicates the effective value when the heater break alarm function is enabled and output is 100% (heater ON) or 0% (heater OFF.)



● Peak current suppression

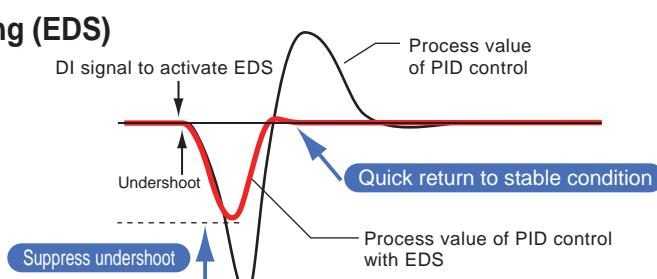
Peak current suppression minimizes the capacity of electrical materials such as power supply equipments, switchboards, power lines, and breakers since this function makes the timing of control output on each channel separate so that the current consumption of the channel with maximum heater capacity is detected as maximum current consumption.



● External disturbance suppression with autotuning (EDS)

EDS with autotuning calculates optimum settings to suppress control disturbance caused by external factors. The function is activated by a DI signal to adjust control output (feed-forward) to compensate for the disturbance.

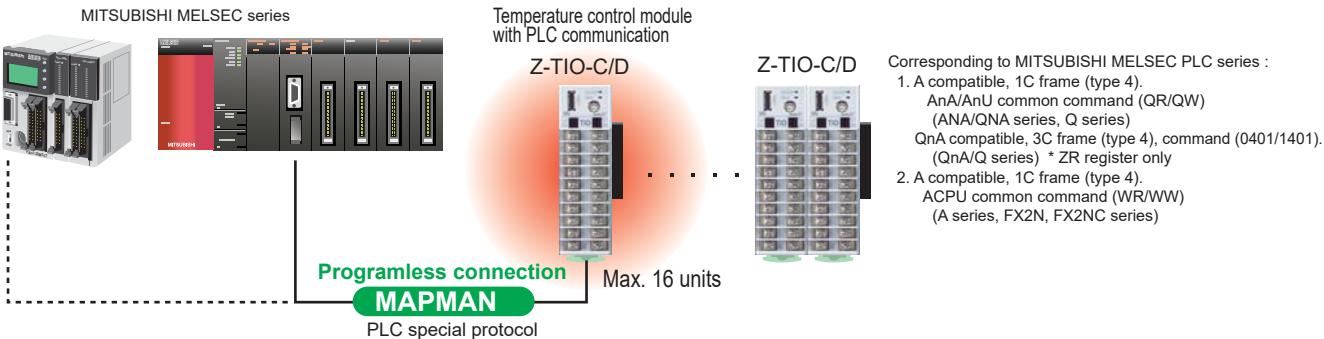
It is suitable for an application in which external disturbance can be predicted, such as wafer-in/out in semiconductor manufacturing equipment, and during injection in injection molding machine.



Communication

Programless connection to PLCs

(Temperature control module with PLC communication : Z-TIO-C/D)



Open Network Connectivity

Ethernet
MODBUS/TCP
Ethernet MAPMAN EtherCAT®



CC-Link Communication Converter Ethernet (Modbus/TCP) Communication Converter DeviceNet Communication converter



MECHATROLINK



COM-ME

● COM-ME-1

Modbus/TCP communication
Ethernet communication Modbus/TCP
Physical layer: 100BASE-TX
User layer: Modbus/TCP
Port spec.: RJ-45 x 2 port
IP Address: 0.0.0.0~255.255.255.255
* Local backloop address (127.0.1~127.255.255.254) can not be used.
Subnet mask: 0.0.0.0~255.255.255.255

● COM-ME-3

EtherCAT communication
Device type: No profile
Physical layer: 100BASE-TX
User layer: EtherCAT
Correspondence protocol: CAN application protocol over EtherCAT
Communication object: SDO, PDO
Connector type: RJ-45 (2 ports)
PDO data length: Max. 1024byte
Both RxPDO (Output) and TxPDO (Input)
Synchronous mode: Free Run

● COM-ME-6

Ethernet (Ethernet MAPMAN) Communication
Physical layer: 10BASE-T/100BASE-TX Automatic recognition
* Only 100BASE-TX can be used under Daisy Chain network
User layer: TCP/IP, Dedicated Mitsubishi PLC protocol
Port spec: RJ-45 x 2 port
IP Address: 0.0.0~255.255.255.255
* Local backloop address (127.0.1~127.255.255.254) can not be used.
Subnet mask: 0.0.0~255.255.255.255

● COM-ME Common Specifications

Host communication
Interface: RS-485
Communication speed: 9600 bps, 19200 bps, 38400 bps, 57600 bps
Protocol:
1) ANSI X3.28-1976 subcategories 2.5 and B1
2) MODBUS-RTU

Loader communication
Communication speed: 38400 bps
Maximum connections: 1 unit
Connection with a loader communication cable for our USB converter COM-KG (sold separately).

General Specifications

Power supply voltage: 24V DC
Current consumption: 150 mA max.
Rush current: Less than 15A
Allowable ambient temperature: -10 to +55°C
Allowable ambient humidity: 5 to 95%RH
(Absolute humidity: MAX.W.C 29.3 g/m³ dry air at 101.3 kPa)
Weight: Approx. 150 g

COM-JC

CC-Link communication
Protocol: CC-Link Ver.1.10/Ver.2.00
Communication speed: 156 kbps, 625 kbps, 2.5 Mbps
5 Mbps, 10 Mbps
Station number: 1 to 64 (4 stations occupied 1 time,
4 stations occupied 2 times)
1 to 64 (1 stations occupied 1 time)
Connection cable: CC-Link dedicated cable Ver.1.10

Communication to SRZ

Connection module: Z-TIO-A/B, Z-DIO

Maximum connection

Total module 31 modules
Same function module: 16 modules

Communication method: RS-485

Protocol: Modbus-RTU

General Specifications

Power supply voltage: 24V DC
Current consumption: Less than 120mA
Rush current: Less than 12A
Weight: 220g
External dimensions: 30 x 125 x 110mm (W x H x D)

COM-JL

Ethernet communication
Physical layer:
Ethernet
10BASE-T/100BASE-TX automatic recognition
Application layer: Modbus/TCP
Communication data: Based on Modbus message format
Connector type: RJ-45

Communication to SRZ

Connection module: Z-TIO-A/B, Z-DIO
Maximum connection
Total module 31 modules

Same function module: 16 modules

Communication method: Based on RS-485

Protocol: Modbus-RTU

General Specifications

Power supply voltage: 24V DC
Current consumption: Less than 110mA
Weight: Approx. 180g
External dimensions: 30 x 125 x 110mm (W x H x D)

COM-JH

DeviceNet Communication
Protocol: DeviceNet
Connection method:
Multi-drop connection, T-branch connection
[Terminating resistor (121Ω, 1/4W) is necessary]
Communication speed: 125 kbps, 250 kbps, 500 kbps
Error control: CRC error
Node address (MAC ID) duplication check
Max number of connection nodes: 64 (including master)

Communication to SRZ

Connection module: Z-TIO-A/B, Z-DIO
Maximum connection
Total module 31 modules
Same function module: 16 modules

Communication method: RS-485

Protocol: Modbus-RTU

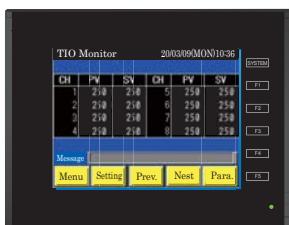
General Specifications

Power supply voltage: 24V DC
Current consumption: Less than 80mA
Rush current: Less than 12A
Weight: Open-style connector type: 120g
Micro-style connector type: 200g
External dimensions: 30 x 125 x 110mm (W x H x D)

Display Unit

Operation Panel : OPC-TS2060

5.7 inches TFT color LCD operation panel



| TIO Monitor 20/03/09(MON)10:36 | | | | | |
|--------------------------------|-----|-----|----|-----|-----|
| CH | PV | SV | CH | PV | SV |
| 1 | 250 | 250 | 5 | 250 | 250 |
| 2 | 250 | 250 | 6 | 250 | 250 |
| 3 | 250 | 250 | 7 | 250 | 250 |
| 4 | 250 | 250 | 8 | 250 | 250 |

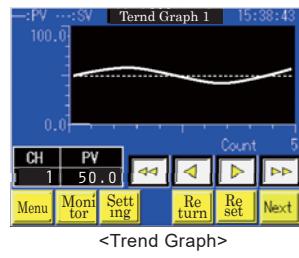
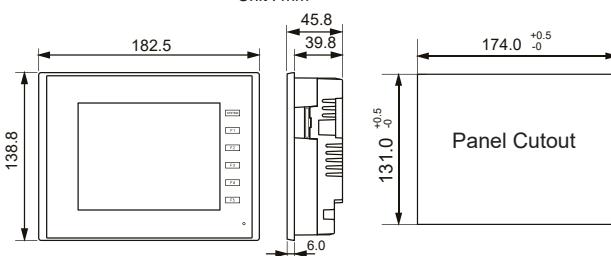
<PV/SV monitor>

| TIO Alarm Monitor 20/03/09(MON)10:36 | | | | | | | |
|--------------------------------------|----|----|----|----|----|----|----|
| CH | E1 | E2 | E3 | E4 | CH | E1 | E2 |
| 1 | ■ | | | | 5 | | |
| 2 | | ■ | | | 6 | | |
| 3 | | ■ | ■ | | 7 | ■ | ■ |
| 4 | | | | | 8 | | |

<Alarm monitor>

External Dimension

Unit : mm



<Trend Graph>

OPC-TS2060 Specifications

Display : TFT color LCD

Power supply voltage : 24V DC

Power consumption : Less than 13W

Ambient temperature : 0 to 50°C

Ambient humidity : Less than 85% RH

Waterproof/Dustproof : IP65

Weight : 580g

Compliance : UL, cUL, CE marking

Communication with a PC via USB port (Loader communication)

Easy parameter setup via USB loader port with PROTEM2 software (Loader communication)

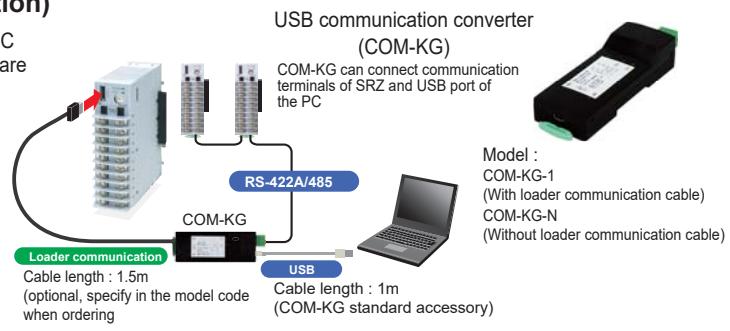
The SRZ module has a standard loader port on the front panel to connect to a PC USB port via COM-KG (USB communication converter). Using PROTEM2 software on the PC, parameter settings can be easily saved on the PC, and the same parameter settings are easily copied to other SRZ modules.

Easy data monitoring and logging with PROTEM2 software

The Win-UCI software enables data monitoring and logging on the PC via communication terminals of SRZ. When SRZ communication terminals are connected to COM-KG (see the diagram below), the USB port can be used on the PC side.

The Loader port is only for parameter setup

• Win-UCI for SRZ is coming soon on the RKC Instrument website (www.rkcinst.com).



Specifications

Temperature Control Module (Z-TIO)

Input

Universal input

Number of inputs
4 or 2 channel (Isolated between inputs)

Input
a) Temperature, Current, Low voltage input group
Thermocouple : K, J, E, T, R, S, B, N (JIS/IEC)
PLII (NBS), W5Re/W26Re (ASTM)
RTD : Pt100 (JIS/IEC), JPt100 (JIS)
• 3-wire system
Low voltage (Input impedance : More than 1MΩ)
0 to 1V DC, 0 to 100mV, 0 to 10mV DC
Current (Input impedance : 50Ω)
4 to 20mA, 0 to 20mA

b) High voltage input group
High voltage (Input impedance : 1MΩ)
-1 to +1V DC, 0 to 5V DC, 1 to 5V DC, 0 to 10V DC
• Available for feedback resistance input

Sampling time : 0.25sec

Influence of external resistance : 0.125μV/V (Thermocouple input)
Influence of lead resistance : 0.02% of reading/Ω (RTD input)

• Maximum 10Ω per wire

Input break action
a) Thermocouple input : Up-scale/Down-scale (Selectable)
b) RTD input : Up-scale

c) Low voltage input : Up-scale/Down-scale (Selectable)

d) Current input : Value around 0mA

e) High voltage input : Value around 0V

Input short action : Down-scale (RTD input)

Input digital filter : 0.1 to 100.0 sec. (OFF when 0 is set.)

PV bias : -span to +span

PV ratio : 0.500 to 1.500

Control

- a) Brilliant II PID control
 - Direct action/Reverse action is selectable
- b) Brilliant II PID control (Heat/Cool type)
- c) Position proportioning control without feedback resistance
 - a), c) is selectable
 - With auto-tuning and start-up tuning (Except for position proportioning control)
- a) Proportional band :
 - Temperature input : 0 to input span (°C, °F)
 - Voltage/Current input : 0.0 to 1000.0% of input span
 - Differential gap at ON/OFF control (High/Low individual setting) : Temperature input : 0 to input span (°C, °F)
 - Voltage/Current input : 0.0 to 100.0% of input span
- b) Integral time : 0 to 3600 sec or 0.0 to 1999.9 sec (selectable)
- c) Derivative time : 0 to 3600 sec or 0.0 to 1999.9 sec (selectable)
- d) Cool side proportional band :
 - Temperature input : 1(0.1, 0.01) to input span (°C, °F)
 - Voltage/Current input : 0.1 to 1000.0% of input span
- e) Cool side Integral time :
 - 0 to 3600 sec or 0.0 to 1999.9 sec (selectable)
- f) Cool side Derivative time :
 - 0 to 3600 sec or 0.0 to 1999.9 sec (selectable)
- g) Overlap/Deadband
 - Temperature input : -span to +span (°C, °F)
 - Voltage/Current input : -100.0 to +100.0% of input span
- h) Control response : Slow, Medium, Fast
- i) Ramp-to-setpoint : 0 to span per Time
 - (Time is settable between 1 and 3600 sec)
 - Up/Down individual setting
- j) Output limiter : -5.0 to +105.0% (High/Low individual setting)
- k) Output change rate limiter : 0.0 to 100.0%/sec
 - (Up/Down individual setting)
- l) Proportional cycle time : 0.1 to 100.0 sec
- m) Cool side proportional cycle time : 0.1 to 100.0 sec
- n) Manual reset : -100.0 to +100.0%
- o) Output at Control Stop mode : -5.0 to +105.0%
 - (Heat side/Cool side individual setting)

Performance

| Input | Input Range | Accuracy |
|------------------------|--------------------------------|---------------------------|
| K, J, T, PLII, E | Less than -100°C (-148°F) | ±2.0°C (±3.6°F) |
| | -100 to +500°C (-148 to 932°F) | ±1.0°C (±1.8°F) |
| | More than 500°C (932°F) | ±(0.2% of reading+1digit) |
| N, S, R, W5Re/W26Re | Less than 1000°C (1832°F) | ±2.0°C (±3.6°F) |
| | More than 1000°C (1832°F) | ±(0.2% of reading+1digit) |
| | | |
| B | Less than 400°C (752°F) | ±70.0°C (±126°F) |
| | 400 to 1000°C (752 to 1832°F) | ±2.0°C (±3.6°F) |
| | More than 1000°C (1832°F) | ±(0.2% of reading+1digit) |
| Pt100, JPt100 | Less than 200°C (392°F) | ±0.4°C (±0.8°F) |
| | More than 200°C (392°F) | ±(0.2% of reading+1digit) |
| DC V, DC A | ±0.2% of span | |
| FBR input | ±1.0% of span +1digit | |

• Cold junction temperature compensation error when close horizontal mounting
±1.0°C (1.8°F) [Terminal type], ±2.0°C (3.6°F) [Connector type]

Insulation resistance

More than 20MΩ (500V DC) between measured terminals and ground
More than 20MΩ (500V DC) between power terminals and ground

More than 20MΩ (500V DC) between measured and power terminals

Dielectric voltage

750V AC for one minute between measured terminals and ground
750V AC for one minute between power terminals and ground
750V AC for one minute between measured and power terminals

Output

Number of outputs : 4 points or 2 points

Output

- a) Relay contact output, Form a contact
250V AC 3A (Resistive load)
- b) Voltage pulse output, 0/12V DC
(Load resistance : More than 600Ω)
 - Power supply and output are not isolated

c) Current output, 4 to 20mA DC, 0 to 20mA DC
(Load resistance : Less than 600Ω)

• Power supply and output are not isolated.

d) Continuous voltage output

1 to 5V, 0 to 5V DC, 1 to 5V DC, 0 to 10V DC

(Load resistance : More than 1kΩ)

• Power supply and output are not isolated.

e) SSR (Triac) output, Rated current : 0.5A

f) Open collector output (Sink type)

Load current : Less than 100mA

Event (Alarm) function

Number of events : Up to 4 points per channel

Event type

Process high, Process low, Deviation high, Deviation low, Deviation high/low, Band, Set value high, Set value low, MV value high, MV value low, Cool side MV value high, Cool side MV value low, FBR value high, FBR value low,

LBA (Control loop break alarm), Deviation high between channel, Deviation low between channel, Deviation high/low between channel, Deviation band between channel LBA, Temperature rise completion

• LBA is assignable to event 4.

• Temperature rise completion is assignable to event 3.

a) Hold/Re-hold action is configurable.

• Valid for deviation/band/process alarm only.

b) Energized/de-energized action is configurable.

c) Delay timer : 0 to 1800sec

d) Interlock (latch) function is configurable.

Heater break alarm function

Number of alarms : 4 or 2 points (1 point per CT input)

CT type : CTL-6-P-N : 0 to 30A

CTL-12-S56-10L-N : 0 to 100A

Input accuracy

±(5% of input value + 1 digit) or 2A (whichever is larger)

Communication function

Communication method : RS-485

Communication speed : 4800bps, 9600bps, 19200bps, 38400bps

Protocol

a) ANSI X3.28 sub-category 2.5B4 (RKC standard)

b) MODBUS-RTU

c) PLC special protocol (Mapman) : Z-TIO-C/D module

Corresponding to MITSUBISHI MELSEC PLC series :

1. A compatible, 1C frame (type 4).

AnA/AnU common command (QR/QW)

(ANA/QNA series, Q series)

QnA compatible, 3C frame (type 4), command (0401/1401)

(QnA/Q series) • ZR register only

2. A compatible, 1C frame (type 4).

ACPU common command (WR/WW)

(A series, FX2N, FX2NC series)

Bit format

a) RKC standard protocol

Start bit : 1, Data bit : 7 or 8,

Parity bit : 1 (odd or even) or none, Stop bit : 1 or 2

b) MODBUS protocol

Start bit : 1, Data bit : 8 (binary or byte data),

Parity bit : 1 (odd or even) or none, Stop bit : 1

Maximum connection

Z-TIO-A/B: 31 modules

Z-TIO-C/D: 16 modules

Multi-Memory Area (recipe)

Number of areas : 8 areas (recipes) per channel

Stored parameters

Set value (SV), Event set values 1 to 4, LBA dead band, Proportional band, Integral time, Derivative time, Cool side proportional band, Cool side integral time, Cool side derivative time, Overlap/Deadband, Manual reset, Control response parameter, Ramp-to-setpoint (Up/Down), Soak time

Linking area number

Other functions

a) Remote setpoint input

b) Temperature ratio setting

c) Cascade control mode

d) Output ratio distribution function

Function which distributes the control output value of the master channel to the Z-DIO/TIO module output.

e) EDS function

Function which suppresses overshoot and undershoot.

f) Auto-temperature-rise with learning function

Function which achieves temperature uniformity at ramp-up in the same control group while learning function calculates optimum parameter settings for this function.

Up to 16 groups can be configured within modules which are connected each other by connectors on the base

g) Peak current suppression function

This function is effective for modules connected each other by connectors on the base

• The peak current suppression function is performed in coupled modules.

h) Master-slave Mode

With this function, when a mode of Mode-master channel is changed, the mode of all slave channels (preset) will be also automatically changed. Modes can be selected among various mode function such as memory area (recipe).

Specifications

Digital Input/Output Module (Z-DIO)

Digital Input

Number of inputs : 8 points
• Isolated input (4 points/common)
Input method
Voltage contact input
Open : Less than 5.0V, Close : More than 17.5V
Contact current : Less than 3.0mA
Allowable input voltage : Less than 26.4V DC
Function : Interlock reset, RUN/STOP, Remote/Local, Auto/Manual, Memory area selection, External disturbance suppression
Function allocation : See digital input allocation table

Digital Output

Number of outputs : 8 points (4 points/common)
Output signal
a) Relay contact output, Form A Contact
250V AC 1A, 30V DC 1A (Resistive load)
b) Open collector output (Sink type)
Allowable load current : Less than 100mA
Load voltage : Less than 30V
Minimum load : 0.5mA
ON voltage : Less than 2.0V (at maximum load current)
Leakage current at OFF : Less than 0.1mA
Function :
Event 1 output (CH1 to CH4), Event 2 output (CH1 to CH4)
Event 3 output (CH1 to CH4), Event 4 output (CH1 to CH4)
HBA output, Burn-out status output, Temperature rise completion output, Manual output
Function allocation : See output allocation table

Communication Function

Communication method : RS-485
Communication speed : 4800bps, 9600bps, 19200bps, 38400bps
Protocol
a) ANSI X3.28 sub-category 2.5B4 (RKC standard)
b) MODBUS-RTU
Bit format
a) RKC standard protocol
Start bit : 1
Data bit : 7 or 8
Parity bit : 1 (odd or even) or none
Stop bit : 1 or 2
b) MODBUS protocol
Start bit : 1
Data bit : 8 (binary or byte data)
Parity bit : none
Stop bit : 1
Maximum connection : 16 units

Communication Extension Module (Z-COM)

Communication Function

Communication method : RS-485/RS-422A
Communication speed : 4800bps, 9600bps, 19200bps, 38400bps
Protocol
a) ANSI X3.28 sub-category 2.5B4 (RKC standard)
b) MODBUS-RTU
c) PLC special protocol (Mapman)
Corresponding to PLC
MITSUBISHI MELSEC series
Ana/AnU common command (QR/QW)
(ANA/QNA series, Q series)
OMRON SYSMAC series
C mode command (WD/RD/WE/RE)
Bit format

- a) RKC standard protocol
Start bit : 1
Data bit : 7 or 8
Parity bit : 1 (odd or even) or none
Stop bit : 1 or 2
- b) MODBUS protocol
Start bit : 1
Data bit : 8 (binary or byte data)
Parity bit : 1 (odd or even) or none
Stop bit : 1
- c) PLC special protocol (Mapman)
Start bit : 1
Data bit : 7 or 8
Parity bit : 1 (odd or even) or none
Stop bit : 1 or 2

Communication allocation
Communication 1 (COM PORT 1 to 2)
RKC standard communication or MODBUS protocol
Communication 2 (COM PORT 3 to 4)
RKC standard communication, MODBUS protocol or PLC special protocol (Mapman)

Maximum connection
RKC standard protocol, MODBUS protocol : 16 units
PLC special protocol (Mapman) : 4 units

Maximum connection function module
Same function module : 16 units
Total function module : 31 units

CT (Current transformer) Input Module (Z-CT)

Input

Number of inputs : 12 points
CT type and Input range
CTL-6-P-Z : 0.0 to 10.0A
CTL-6-P-N : 0.0 to 30.0A
CTL-12-S56-10L-N : 0.0 to 100.0A
Sampling cycle : 3 sec
Input accuracy :
CTL-6-P-Z : ±0.3A
CTL-6-P-N : ±2% of reading or ±1.0A
CTL-12-S56-10L-N : ±2% of reading or ±1.0A

Event (Alarm)

Alarm type : Heater break alarm (HBA) and Heater overcurrent alarm
• Interlock (latch) function is configurable.
• Alarm delay time : 0 to 255 times
Setting method: Via communication or push-button switch
• Automatic alarm setting function is available.
CT allocation : Module address setting and channel setting

Communication Function

Same as DIO module communication function

Z-TIO, Z-DIO, Z-CT, Z-COM Common Specifications

General Specifications

Supply voltage : 21.6 to 26.4V DC (Including supply voltage variation)

Rating : 24V DC

Power consumption

- a) Z-TIO : Less than 140mA, Surge current : Less than 10A
- b) Z-DIO : Less than 70mA, Surge current : Less than 10A
- c) Z-CT : Less than 70mA, Surge current : Less than 10A
- d) Z-COM : Less than 30mA, Surge current : Less than 10A

Power failure

A power failure of 4m sec or less will not affect the control action.
• If power failure of more than 20m sec occurs, controller will restart with the state of HOT or COLD start. (Only Z-TIO)

Memory backup

Backed up by non-volatile memory (FRAM)
• Data retaining period : Approx. 10 years
• Number of writing : Approx. 10,000,000,000 times.
(Depending on storage and operating conditions.)

Ambient temperature : -10 to +50°C (14 to 122°F)

Ambient humidity : 5 to 95% RH (Non condensing)

• Absolute humidity : MAX.W.C 29.3g/m³ dry air at 101.3kPa

Weight

Z-TIO

Terminal type : Approx 130g (2ch type), Approx 160g (4ch type)
Connector type : Approx 120g (2ch type), Approx 140g (4ch type)

Z-DIO

Terminal type : Approx 150g (DI/DO 8ch type)
Approx 120g (DI 8ch type)
Approx 140g (DO 8ch type)
Connector type : Approx 130g (DI/DO 8ch type)
Approx 100g (DI 8ch type)
Approx 120g (DO 8ch type)

Z-CT

Terminal type : Approx 160g
Connector type : Approx 140g

Z-COM : Approx 110g

Operating environment

Free from corrosive and flammable gas and dust.

Free from external noise, vibration, shock and exposure to direct sunlight.

Compliance with Standards

CE Mark, UL, c-UL, RCM mark

External Dimensions

Temperature Control Module (Z-TIO)

Digital Input/Output Module (Z-DIO)

Current transformer (CT) Input Module (Z-CT)

● Terminal Type

● Connector Type

● Communication Extension Module (Z-COM)

● Body

● Base

● Secure approximately 50 mm for the

connectors and wiring, depending on

the connector type

● Secure approximately 50 mm for the

connectors and wiring, depending on

the connector type

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Model and Suffix Code

● 4ch type Temperature Control Module (Z-TIO-A/C)

| Specifications | Z-TIO-A (Standard type) Z-TIO-C (PLC special protocol : MAPMAN) | Hardware coding | | | | | | Quick start code | | Control output |
|--------------------|--|-----------------|---|---|---|---|---|---------------------|---|---|
| | | ① | ② | ③ | ④ | ⑤ | ⑥ | ⑦ | ⑧ | |
| Wiring method | ① Terminal type Connector type | T C | | | | | | | | PID control Heat/Cool PID control Position proportional PID control without FBR |
| Output 1 | ② See Output Code Table | | | | | | | | | CH1 output CH1 Heat output CH1 Open output |
| Output 2 | ③ See Output Code Table | | | | | | | | | CH2 output CH1 Cool output CH1 Close output |
| Output 3 | ④ See Output Code Table | | | | | | | | | CH3 output CH2 Heat output CH2 Open output |
| Output 4 | ⑤ See Output Code Table | | | | | | | | | CH4 output CH2 Cool output CH2 Close output |
| CT input | ⑥ Not supplied ⑦ CT input 4 points | N A | | | | | | | | |
| Quick start code | ⑦ No quick start code (Default setting) Specify quick start code 1 Specify quick start code 1 and 2 (See page 7) | | | | | | | N 1 2 | | |
| Quick start code 1 | No quick start code PID control with AT (Reverse action) PID control with AT (Direct action) | | | | | | | No symbol F D | | |
| Control method | ⑧ Heat/Cool PID control with AT (Air cooling type) (CH2 and CH4 are unused.) Heat/Cool PID control with AT (Water cooling type) (CH2 and CH4 are unused.) Heat/Cool PID control with AT (CH2 and CH4 are unused.) Position proportional PID control without FBR (CH2 and CH4 are unused.) | | | | | | | A W G Z | | |
| Input range | ⑨ No quick start code See Input Range Code Table | | | | | | | No symbol □□□ | | |
| Instrument version | ⑩ Version symbol | | | | | | | Y | | |

● 2ch type Temperature Control Module (Z-TIO-B/D)

| Specifications | Z-TIO-B (Standard type) Z-TIO-D (PLC special protocol : MAPMAN) | Hardware coding | | | | | | Quick start code | | Control output |
|--------------------|--|-----------------|---|---|---|---|---|---------------------|---|---|
| | | ① | ② | ③ | ④ | ⑤ | ⑥ | ⑦ | ⑧ | |
| Wiring method | ① Terminal type Connector type | T C | | | | | | | | |
| Output 1 | ② See Output Code Table | | | | | | | | | CH1 output CH1 Heat output CH1 Open output |
| Output 2 | ③ See Output Code Table | | | | | | | | | CH2 output CH1 Cool output CH1 Close output |
| CT input | ④ Not supplied ⑤ CT input 2 points | N A | | | | | | | | |
| Option | ⑤ Not supplied | N | | | | | | | | |
| Quick start code | ⑥ No quick start code (Default setting) Specify quick start code 1 Specify quick start code 1 and 2 (See page 7) | | | | | | | N 1 2 | | |
| Quick start code 1 | No quick start code PID control with AT (Reverse action) PID control with AT (Direct action) | | | | | | | No symbol F D | | |
| Control method | ⑦ Heat/Cool PID control with AT (Air cooling type) (CH2 and CH4 are unused.) Heat/Cool PID control with AT (Water cooling type) (CH2 and CH4 are unused.) Heat/Cool PID control with AT (CH2 and CH4 are unused.) Position proportional PID control without FBR (CH2 and CH4 are unused.) | | | | | | | A W G Z | | |
| Input range | ⑧ No quick start code See Input Range Code Table | | | | | | | No symbol □□□ | | |
| Instrument version | Version symbol | | | | | | | Y | | |

Input Range Code Table

Thermocouple

| Input | Code | Range | Input | Code | Range |
|-------|------------|---------------------|-------|------------|---------------------|
| K | K '35 | -200.0 to +400.0°C | J | J '27 | -200.0 to +400.0°C |
| | K '40 | -200.0 to +800.0°C | | J '32 | -200.0 to +800.0°C |
| | K '09 | 0.0 to 400.0°C | | J '08 | 0.0 to 400.0°C |
| | K '10 | 0.0 to 800.0°C | | J '09 | 0.0 to 800.0°C |
| | K '42 | -200.0 to +1372.0°C | | J '29 | -200.0 to +1200.0°C |
| | K '02 | 0 to 400°C | | J '02 | 0 to 400°C |
| | K '04 | 0 to 800°C | | J '04 | 0 to 800°C |
| | K '41 | -200 to +1372°C | | J '15 | -200 to +1200°C |
| | K 'C7 | -328 to +2501°F | | J '86 | 0.0 to 800.0°F |
| | K 'A4 | 0.0 to 800.0°F | | J 'B9 | -328 to +2192°F |
| K 'A1 | 0 to 800°F | | J 'A1 | 0 to 800°F | |
| | K 'A2 | 0 to 1600°F | | J 'A2 | 0 to 1600°F |

| Input | Code | Range |
|-------|-------|---------------------|
| T | T '19 | -200.0 to +400.0°C |
| T | T 'C5 | -328 to +752.0°F |
| T | T 'C6 | 0.0 to +752.0°F |
| S | S '06 | -50 to +1768°C |
| S | S 'A7 | -58 to +3214°F |
| R | R '07 | -50 to +1768°C |
| R | R 'A7 | -58 to +3214°F |
| E | E '20 | -200.0 to +1000.0°C |
| E | E 'B2 | 0.0 to +800.0°F |
| E | E 'B1 | -328 to +1832°F |

| Input | Code | Range |
|---------|-------|---------------|
| B | B '03 | 0 to 1800°C |
| B | B 'B1 | 32 to 3272°F |
| N | N '02 | 0 to +1200°C |
| N | N 'A6 | 32 to +2372°F |
| PLII | A '02 | 0 to 1390°C |
| (NBS) | A 'A2 | 0 to 2534°F |
| WRe/WRe | W '03 | 0 to 2300°C |
| (ASTM) | W 'B1 | 32 to 4208°F |

DC Current • Voltage

| Input | Code | Range |
|------------|-------|---------------|
| 0 to 10mV | 1 '01 | |
| 0 to 100mV | 2 '01 | 0.0 to 100.0% |
| 0 to 1V | 3 '01 | |
| 0 to 5V | 4 '01 | |

| Input | Code | Range |
|-----------|-------|---------------|
| 0 to 10V | 5 '01 | |
| 1 to 5V | 6 '01 | 0.0 to 100.0% |
| 0 to 20mA | 7 '01 | |
| 4 to 20mA | 8 '01 | |

- Quick start code 2 tells the factory to ship with each parameter preset to the values detailed as specified by the customer.
- Quick start code is not necessarily specified when ordering, unless the preset is requested.
- These parameters are software selectable items and can be re-programmed in the field via the manual.

Quick Start Code 2

| Specifications | Quick Start Code 2 | ① ② ③ ④ ⑤ ⑥ | | | | | | N | P | S |
|------------------------|--|-------------|---|---|---|---|---|------------------|---|---|
| | | ① | ② | ③ | ④ | ⑤ | ⑥ | | | |
| Event 1 type | ① See Event Type Code Table | | | | | | | | | |
| Event 2 type | ② See Event Type Code Table | | | | | | | | | |
| Event 3 type | ③ See Event Type Code Table | | | | | | | | | |
| Event 4 type | ④ See Event Type Code Table | | | | | | | | | |
| CT type | ⑤ No CT input CTL-6-P-N CTL-12-S56-10L-N | | | | | | | | | |
| Communication Protocol | ⑥ ANSI/RKC standard protocol MODBUS protocol PLC special protocol (MAPMAN) (Mitsubishi MELSEC A/Q series) • Only Z-TIO-C/D PLC special protocol (MAPMAN) (Mitsubishi MELSEC FX series) • Only Z-TIO-C/D | | | | | | | 1 2 3 5 | | |

Event Type Code Table

| Event Type | Code | Event Type | Code |
|------------------------------------|------|---------------------------------------|------|
| No event | N | Deviation High with Alarm Re-Hold | Q |
| Deviation High | A | Deviation Low with Alarm Re-Hold | R |
| Deviation Low | B | Deviation High/Low with Alarm Re-Hold | T |
| Band | D | Set value High | V |
| Deviation High with Alarm Hold | E | Set value Low | W |
| Deviation Low with Alarm Hold | F | MV value High | 1 |
| Deviation High/Low with Alarm Hold | G | MV value Low | 2 |
| Process High | H | Cool side MV value High | 3 |
| Process Low | J | Cool side MV value Low | 4 |
| Process High with Alarm Hold | K | LBA (Loop break alarm) | 1 |
| Process Low with Alarm Hold | L | Temperature rise completion | 2 |

¹ LBA is available with event 4 only.

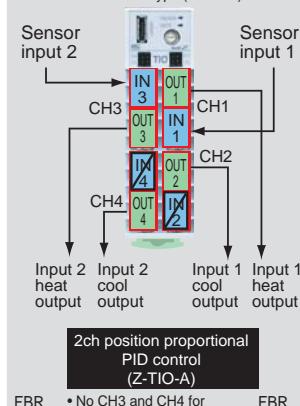
² Temperature rise completion is available with event 3 only.

Input/Output configuration

(Heat/Cool PID control or Position proportional PID control)

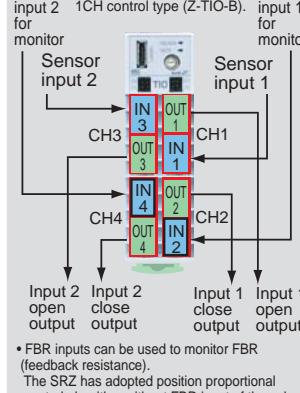
2ch heat/cool PID control (Z-TIO-A)

• No CH3 and CH4 for 1CH control type (Z-TIO-B).



2ch position proportional PID control (Z-TIO-B)

• No CH3 and CH4 for 1CH control type (Z-TIO-B).



• FBR inputs can be used to monitor FBR (feedback resistance).

The SRZ has adopted position proportional control algorithm without FBR input of the valve in position proportional control.

● Digital Input/Output Module (Z-DIO-A)

| Specifications | Z-DIO-A | Hardware coding | | | | Quick start code | | | |
|---|---|-----------------|---|---|---|------------------|---|---|---|
| | | ① | ② | ③ | ④ | ⑤ | ⑥ | ⑦ | ⑧ |
| Wiring method | ① Terminal type | T | | | | | | | |
| | ② Connector type | C | | | | | | | |
| Number of digital input (DI) | ② Not supplied | N | | | | | | | |
| | ② DI 8 points | A | | | | | | | |
| Digital output (DO) signal | ③ Not supplied | N | | | | | | | |
| | ③ Relay contact output, 8 points | M | | | | | | | |
| | ③ Open Collector output, 8 points | D | | | | | | | |
| Quick start code | ④ No quick start code (Default setting) | N | | | | | | | |
| | ④ Specify quick start code | 1 | | | | | | | |
| Quick start code | ⑤ No quick start code | No symbol | | | | | | | |
| | ⑤ No digital input | N | | | | | | | |
| | ⑤ See DI allocation table | | □ | | | | | | |
| Digital output (DO) allocation (DO1 to DO4) | ⑥ No quick start code | No symbol | | | | | | | |
| | ⑥ No digital output | N | | | | | | | |
| | ⑥ See DO1 to 4 allocation table | | □ | | | | | | |
| Digital output (DO) allocation (DO5 to DO8) | ⑦ No quick start code | No symbol | | | | | | | |
| | ⑦ No digital output | N | | | | | | | |
| | ⑦ See DO5 to 8 allocation table | | □ | | | | | | |
| Communication protocol | ⑧ ANSI/RKC standard protocol | 1 | | | | | | | |
| | ⑧ MODBUS protocol | 2 | | | | | | | |

DO1 to 4 Allocation Table

| Code | Digital output | | | |
|------|-------------------|----------------------------|------------------|-------------------|
| | DO 1 | DO 2 | DO 3 | DO 4 |
| 01 | DO1 manual output | DO manual output | DO manual output | DO4 manual output |
| 02 | Event 1 (All CH) | Event 2 (All CH) | Event 3 (All CH) | Event 4 (All CH) |
| 03 | Event 1 (CH1) | Event 2 (CH1) | Event 3 (CH1) | Event 4 (CH1) |
| 04 | Event 1 (CH2) | Event 2 (CH2) | Event 3 (CH2) | Event 4 (CH2) |
| 05 | Event 1 (CH3) | Event 2 (CH3) | Event 3 (CH3) | Event 4 (CH3) |
| 06 | Event 1 (CH4) | Event 2 (CH4) | Event 3 (CH4) | Event 4 (CH4) |
| 07 | Event 1 (CH1) | Event 1 (CH2) | Event 1 (CH3) | Event 1 (CH4) |
| 08 | Event 2 (CH1) | Event 2 (CH2) | Event 2 (CH3) | Event 2 (CH4) |
| 09 | Event 3 (CH1) | Event 3 (CH2) | Event 3 (CH3) | Event 3 (CH4) |
| 10 | Event 4 (CH1) | Event 4 (CH2) | Event 4 (CH3) | Event 4 (CH4) |
| 11 | TIO HBA (CH1) | TIO HBA (CH2) | TIO HBA (CH3) | TIO HBA (CH4) |
| 12 | Burnout (CH1) | Burnout (CH2) | Burnout (CH3) | Burnout (CH4) |
| 13 | Temperature rise | HBA (Comprehensive output) | Burnout (All CH) | DO4 manual output |

DO5 to 8 Allocation Table

| Code | Digital output | | | |
|------|-----------------------------|----------------------------|-------------------|-------------------|
| | DO 5 | DO 6 | DO 7 | DO 8 |
| 01 | DO5 manual output | DO6 manual output | DO7 manual output | DO8 manual output |
| 02 | Event 1 (All CH) | Event 2 (All CH) | Event 3 (All CH) | Event 4 (All CH) |
| 03 | Event 1 (CH1) | Event 2 (CH1) | Event 3 (CH1) | Event 4 (CH1) |
| 04 | Event 1 (CH2) | Event 2 (CH2) | Event 3 (CH2) | Event 4 (CH2) |
| 05 | Event 1 (CH3) | Event 2 (CH3) | Event 3 (CH3) | Event 4 (CH3) |
| 06 | Event 1 (CH4) | Event 2 (CH4) | Event 3 (CH4) | Event 4 (CH4) |
| 07 | Event 1 (CH1) | Event 1 (CH2) | Event 1 (CH3) | Event 1 (CH4) |
| 08 | Event 2 (CH1) | Event 2 (CH2) | Event 2 (CH3) | Event 2 (CH4) |
| 09 | Event 3 (CH1) | Event 3 (CH2) | Event 3 (CH3) | Event 3 (CH4) |
| 10 | Event 4 (CH1) | Event 4 (CH2) | Event 4 (CH3) | Event 4 (CH4) |
| 11 | TIO HBA (CH1) | TIO HBA (CH2) | TIO HBA (CH3) | TIO HBA (CH4) |
| 12 | Burnout (CH1) | Burnout (CH2) | Burnout (CH3) | Burnout (CH4) |
| 13 | Temperature rise completion | HBA (Comprehensive output) | Burnout (All CH) | DO8 manual output |

DI Allocation Table

| | Digital input | | | | | | | |
|----|----------------------------------|-------------|-----------------------|-----------------------|--------------------|-----------------------|--------------------|------------------|
| | DI 1 | DI 2 | DI 3 | DI 4 | DI 5 | DI 6 | DI 7 | DI 8 |
| 01 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | Alarm interlock reset | AUTO/MANUAL | |
| 02 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | Alarm interlock reset | LOCAL/REMOTE | |
| 03 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | Alarm interlock reset | Feed-forward start | |
| 04 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | Alarm interlock reset | Soak stop | |
| 05 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | Alarm interlock reset | STOP/RUN | |
| 06 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | AUTO/MANUAL | LOCAL/REMOTE | |
| 07 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | AUTO/MANUAL | Feed-forward start | |
| 08 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | AUTO/MANUAL | Soak stop | |
| 09 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | AUTO/MANUAL | STOP/RUN | |
| 10 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | LOCAL/REMOTE | Feed-forward start | |
| 11 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | LOCAL/REMOTE | Soak stop | |
| 12 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | LOCAL/REMOTE | STOP/RUN | |
| 13 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | EDS start | Soak stop | |
| 14 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | EDS start | STOP/RUN | |
| 15 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | Soak stop | STOP/RUN | |
| 16 | Memory area selection (1 to 8) | | Area set | Alarm interlock reset | AUTO/MANUAL | LOCAL/REMOTE | Feed-forward start | |
| 17 | Memory area selection (1 to 8) | | Area set | Alarm interlock reset | AUTO/MANUAL | LOCAL/REMOTE | Soak stop | |
| 18 | Memory area selection (1 to 8) | | Area set | Alarm interlock reset | AUTO/MANUAL | LOCAL/REMOTE | STOP/RUN | |
| 19 | Memory area selection (1 to 8) | | Area set | Alarm interlock reset | AUTO/MANUAL | EDS start | Soak stop | |
| 20 | Memory area selection (1 to 8) | | Area set | Alarm interlock reset | AUTO/MANUAL | EDS start | STOP/RUN | |
| 21 | Memory area selection (1 to 8) | | Area set | Alarm interlock reset | AUTO/MANUAL | Soak stop | STOP/RUN | |
| 22 | Memory area selection (1 to 8) | | Area set | AUTO/MANUAL | LOCAL/REMOTE | EDS start | Soak stop | |
| 23 | Memory area selection (1 to 8) | | Area set | AUTO/MANUAL | LOCAL/REMOTE | EDS start | STOP/RUN | |
| 24 | Memory area selection (1 to 8) | | Area set | AUTO/MANUAL | LOCAL/REMOTE | Soak stop | STOP/RUN | |
| 25 | Memory area selection (1 to 8) | | Area set | LOCAL/REMOTE | Feed-forward start | Soak stop | STOP/RUN | |
| 26 | Memory area selection (2 points) | Area set | Alarm interlock reset | STOP/RUN | AUTO/MANUAL | LOCAL/REMOTE | Operation mode 1 | Operation mode 2 |
| 27 | Memory area selection (1 to 8) | | Area set | Operation mode 1 | Operation mode 2 | EDS start 1 | EDS start 2 | |
| 28 | Memory area selection (2 points) | Area set | Alarm interlock reset | Area set | AUTO/MANUAL | LOCAL/REMOTE | EDS start 1 | EDS start 2 |
| 29 | EDS start 1 | EDS start 2 | Alarm interlock reset | Area set | AUTO/MANUAL | LOCAL/REMOTE | Operation mode 1 | Operation mode 2 |

• Area setting is set to disabled at the factory.

Operation mode 1 : Only monitoring. (Control stop, Event function OFF)

Operation mode 2 : Monitoring and Event function (Control stop)

● CT (Current transformer) Input Module (Z-CT)

| Specifications | Z-CT-A | Hardware coding | | | | Quick start code | | | |
|------------------------|---|-----------------|---|---|---|------------------|---|---|---|
| | | ① | ② | ③ | ④ | ⑤ | ⑥ | ⑦ | ⑧ |
| Wiring method | ① Terminal type | T | | | | | | | |
| | ① Connector type | C | | | | | | | |
| Quick start code | ② No quick start code (Default setting) | N | | | | | | | |
| | ② Specify quick start code | 1 | | | | | | | |
| CT type | ③ No quick start code | No symbol | | | | | | | |
| | ③ CTL-6-P-N (0 to 30A) | P | | | | | | | |
| | ③ CTL-12-S56-10L-N (0 to 100A) | S | | | | | | | |
| | ③ CTL-6-P-Z (0 to 10A) | Z | | | | | | | |
| Communication protocol | ④ No quick start code | No symbol | | | | | | | |
| | ④ ANSI/RKC standard protocol | 1 | | | | | | | |
| | ④ MODBUS protocol | 2 | | | | | | | |

● Communication Module (Z-COM-A)

| Specifications | Z-COM-A- | Hardware coding | | | | Quick start code | | | |
|--|---|-----------------|---|---|---|------------------|---|---|---|
| | | ① | ② | ③ | ④ | ⑤ | ⑥ | ⑦ | ⑧ |
| COM PORT 1,2 communication | ① RS-422A | 4 | | | | | | | |
| | RS-485 | 5 | | | | | | | |
| COM PORT 3,4 communication | ② RS-422A | 4 | | | | | | | |
| | RS-485 | 5 | | | | | | | |
| Quick start code | ③ No quick start code (Default setting) | N | | | | | | | |
| | ③ Specify quick start code | 1 | | | | | | | |
| COM PORT 1,2 communication protocol | ④ No quick start code | No symbol | | | | | | | |
| | ANSI/RKC standard protocol | 1 | | | | | | | |
| | MODBUS protocol | 2 | | | | | | | |
| COM PORT 3,4 communication protocol | ⑤ No quick start code | No symbol | | | | | | | |
| | ANSI/RKC standard protocol | 1 | | | | | | | |
| | MODBUS protocol | 2 | | | | | | | |
| PLC special protocol (MAPMAN) (Mitsubishi MELSEC A/Q series) | ⑥ PLC special protocol (MAPMAN) (OMRON SYSMAC series) | 3 | | | | | | | |
| | PLC special protocol (MAPMAN) (Mitsubishi MELSEC FX series) | 4 | | | | | | | |
| Maximum channel data (For PLC special communication) | ⑦ No quick start code | No symbol | | | | | | | |
| | 16-channels specification | A | | | | | | | |
| | 32-channels specification | B | | | | | | | |
| | 48-channels specification | C | | | | | | | |
| | 64-channels specification | D | | | | | | | |

Standard accessory
Connector cover
Model : KSRZ-517A

Power supply terminal cover
Model : KSRZ-518A

Model Code

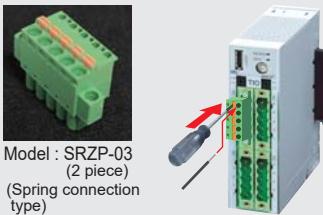
Accessories

Operation Panel (OPC-TS2060)

Compact setting display unit (OP10)

● Accessories

Plug-in connector (For connector type module)

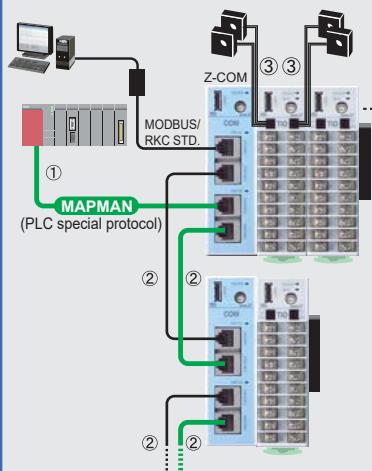


Model : SRZP-03
(2 piece)
(Spring connection type)
Equivalent part :
FKC 2.5/5-STF-5,08 AU
PHOENIX CONTACT

Model : SRZP-02
(2 piece)
(Side screw type)
Equivalent part :
MSTB 2.5/5-STF-5,08AU
PHOENIX CONTACT

Model : SRZP-01
(2 piece),
(Front screw type)
Equivalent part :
FRONT-MSTB 2.5/5-STF-5,08AU
PHENIX CONTACT

Communication cables



① Model :
W-BF-01-3000 (3m)
6 pins RJ45
Spade lug terminal *

* Other types of cables such as
cable with 9-pin D-SUB connector
are also available.
Please contact RKC.

③ Model :
W-BW-03-1000 (1m)
W-BW-03-2000 (2m)
W-BW-03-3000 (3m)

4 pins
Spade lug terminal

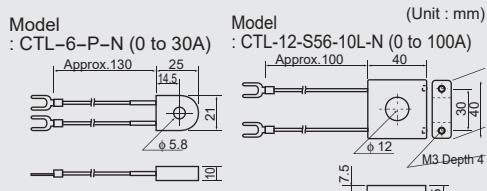
Termination resistor connector



Model : W-BW-01
(For RS-485)

Model : W-BW-02
(For RS-422A)

Current transformer for heater break alarm (HBA)



End plates

Model : DEP-01

To firmly fix the modules,
use end plates on both
sides of the mounted modules
on the DIN rail.



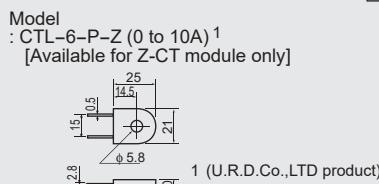
Terminal Cover (For power supply)



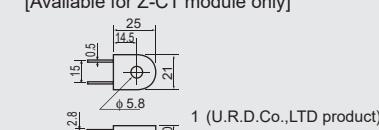
Joint connector cover



Model : KSRZ-518A Model : KSRZ-517A



Model : CTL-6-P-Z (0 to 10A)
[Available for Z-CT module only]



Front terminal cover

Model :
KSRZ-510A



● Operation Panel (OPC-TS2060)

| Specifications | No | Model Code OPC-TS2060- | ① ② ③ |
|----------------------|----|----------------------------------|--------|
| Display method | ① | TFT Color LCD | 1 |
| Available controller | ② | SRZ (MODBUS protocol) | 5 |
| Language | ③ | Japanese English | J E |



Cable

OPC-TS2060

Z-TIO ① V6-MLT (3m)



RS-485 MODBUS

8 pins
Spade lug terminal

Terminal/ Connector Configuration

Temperature Control Module (Z-TIO) Terminal type

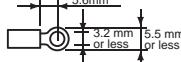
| | | | |
|------------------------------|---|------------------------|---|
| CT4 Input CT *1 2 1 | CT1 Input CT *1 3 4 | No. Description | No. Description |
| 21 | B | Measured Input 3 (CH3) | 11 Control Output 1 (CH1) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| 22 | (1) Thermocouple (2) RTD (3) Voltage/Current | 12 | Control Output 1 (CH1) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| 23 | A | Measured Input 1 (CH1) | 13 A |
| 24 | (1) Thermocouple (2) RTD (3) Voltage/Current | 14 | (1) Thermocouple (2) RTD (3) Voltage/Current |
| 25 | B | Measured Input 4 (CH4) | 15 B |
| 26 | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance | 16 | Control Output 2 (CH2) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| 27 | (W) | 27 | Control Output 3 (CH3) (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance |
| 28 | A | 28 | Control Output 4 (CH4) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| 29 | (1) (2) (3) (4) | 29 | Measured Input 2 (CH2) |
| 30 | NO | 30 | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance |

CT : Current transformer for heater break alarm

Feedback resistance input is used only for monitoring.

<Caution> Voltage / current outputs are not isolated from the power supply voltage.

Screw Size : M3 X 7
Solderless terminal is recommended

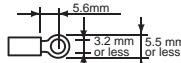


Digital Input/Output Module (Z-DIO) Terminal type

| | | | |
|-----|-------------------------|-----|---|
| No. | Description | No. | Description |
| 21 | DI4 | 11 | COM COM |
| 22 | DI3 | 12 | DO1 24VDC DO1 |
| 23 | DI2 | 13 | DO2 NO |
| 24 | DI1 | 14 | DO3 NO |
| 25 | COM | 15 | DO4 NO (1) NO (2) |
| 26 | 24VDC | 16 | COM 24VDC COM |
| 27 | DI8 | 17 | DO5 DO5 |
| 28 | DI7 | 18 | DO6 NO |
| 29 | DI6 | 19 | DO7 NO |
| 30 | DI5 | 20 | DO8 NO (1) NO (2) |
| | Voltage sink type input | | Digital Output 1 to 4 |
| | Voltage sink type input | | (1) Relay contact (2) Open collector |
| | Voltage sink type input | | Digital Output 5 to 8 |
| | Voltage sink type input | | (1) Relay contact (2) Open collector |

Screw Size : M3 X 7

Solderless terminal is recommended

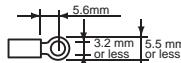


CT (Current transformer) Input Module (Z-CT) Terminal type

| | | | |
|-----|-------------------|-----|-----------------|
| No. | Description | No. | Description |
| 21 | CT9 | 11 | CT1 |
| 22 | COM | 12 | COM |
| 23 | CT8 | 13 | CT2 |
| 24 | COM | 14 | COM |
| 25 | CT7 | 15 | CT3 |
| 26 | CT12 | 16 | CT4 |
| 27 | COM | 17 | COM |
| 28 | CT11 | 18 | CT5 |
| 29 | COM | 19 | COM |
| 30 | CT10 | 20 | CT6 |
| | CT Input 7 to 9 | | CT Input 1 to 3 |
| | CT Input 10 to 12 | | CT Input 4 to 6 |

Screw Size : M3 X 7

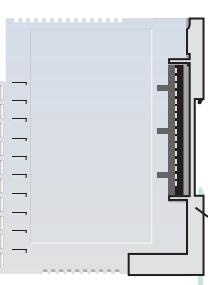
Solderless terminal is recommended



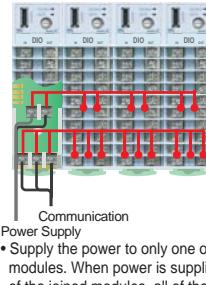
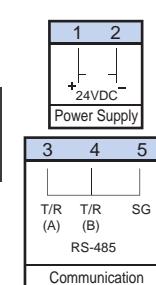
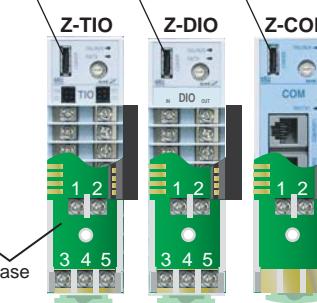
Communication Extension Module (Z-COM)

| | |
|------------|---|
| COM PORT 1 | Communication 1 |
| COM PORT 2 | RKC standard/MODBUS RS-485,422A |
| COM PORT 3 | Communication 2 |
| COM PORT 4 | RKC standard/MODBUS PLC special protocol (Mapman) RS-485,422A |

Z-TIO/DIO/CT/COM



Loader Port



* Z-COM: No.3,4,5 terminals are not mounted.

Temperature Control Module (Z-TIO) Connector type

| | | | |
|------------------|--|---|--|
| CN (Connector) 3 | CT4 Input CT *1 2 1 | CT1 Input CT *1 3 4 | No. Description |
| | 11 | 12 | Measured Input 3 (CH3) |
| | (1) Thermocouple (2) RTD (3) Voltage/Current | (1) Thermocouple (2) RTD (3) Voltage/Current | Control Output 1 (CH1) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| | 13 | 14 | Measured Input 1 (CH1) |
| | (1) Thermocouple (2) RTD (3) Voltage/Current | (1) Thermocouple (2) RTD (3) Voltage/Current | (1) Thermocouple (2) RTD (3) Voltage/Current |
| | 15 | 16 | Measured Input 4 (CH4) |
| | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance | Control Output 2 (CH2) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| | 17 | 18 | Measured Input 2 (CH2) |
| | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance | (1) Thermocouple (2) RTD (3) Voltage/Current (4) Feedback resistance |
| | 19 | 20 | Control Output 4 (CH4) |
| | (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac | (1) Relay contact (2) Open collector | Control Output 3 (CH3) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |

CN (Connector) 4

| | | |
|------------------|-----|--|
| CN (Connector) 4 | CN1 | No. Description |
| | CN1 | 1 Control Output 1 (CH1) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| | CN2 | 2 Control Output 2 (CH2) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| | CN3 | 3 Control Output 3 (CH3) (1) Relay contact (2) Voltage pulse/Voltage/ Current/Open collector (3) Triac |
| | CN4 | 4 Control Output 4 (CH4) (1) Relay contact (2) Open collector |

* For 2CH specifications, connectors CN3 and CN4 are not mounted. *1 : Optional

CT : Current transformer for heater break alarm

Feedback resistance input is used only for monitoring.

<Caution> Voltage / current outputs are not isolated from the power supply voltage.

Digital Input/Output Module (Z-DIO) Connector type

| | | |
|-----|-----|--|
| CN3 | CN1 | No. Description |
| | CN1 | 1 DI4 2 DI3 3 DI2 4 DI1 5 COM |
| | CN2 | Digital Input 1 to 4 Voltage sink type input |
| | CN3 | 1 DI8 2 DI7 3 DI6 4 DI5 5 COM |
| | CN4 | Digital Output 5 to 8 (1) Relay contact (2) Open collector |
| | CN2 | Digital Input 5 to 8 Voltage sink type input |
| | CN1 | 5 COM 24VDC DO1 4 NO DO2 3 NO DO3 2 NO DO4 1 NO (1) NO (2) |

| | | |
|-----|-----|--|
| CN4 | CN2 | No. Description |
| | CN2 | 1 DI8 2 DI7 3 DI6 4 DI5 5 COM |
| | CN1 | Digital Input 5 to 8 Voltage sink type input |
| | CN4 | 1 DI8 2 DI7 3 DI6 4 DI5 5 COM |
| | CN2 | Digital Output 5 to 8 (1) Relay contact (2) Open collector |

CT (Current transformer) Input Module (Z-CT) Connector type

| | | |
|-----|-----|--|
| CN3 | CN1 | No. Description |
| | CN1 | 1 CT9 2 COM 3 CT8 4 CT7 5 CT12 6 COM 7 CT11 8 COM 9 CT10 |
| | CN2 | CT Input 7 to 9 |
| | CN3 | 11 CT1 12 COM 13 CT2 14 COM 15 CT3 16 CT4 17 COM 18 CT5 19 COM 20 CT6 |
| | CN4 | CT Input 1 to 3 |
| | CN2 | 1 CT12 2 COM 3 CT11 4 COM 5 CT10 |
| | CN1 | CT Input 4 to 6 |

| | | |
|-----|-----|--|
| CN4 | CN2 | No. Description |
| | CN2 | 1 CT12 2 COM 3 CT11 4 COM 5 CT10 |
| | CN1 | CT Input 10 to 12 |
| | CN4 | 1 CT14 2 COM 3 CT5 4 COM 5 CT6 |
| | CN2 | CT Input 4 to 6 |

Communication Converter Model Code

● MODBUS/TCP Communication Converter : COM-ME-1

| Specifications | | Model and Suffix Code | | | |
|----------------|---|---|-------------------|-----------|---------------|
| | | COM-ME | | Mandatory | Option |
| Mandatory | Network | Ethernet [MODBUS/TCP] | 1 | -1 | 5 * 02 /□ □ □ |
| | Host communication | RS-485 | 5 | | |
| | Supported Controller | SRZ(Z-TIO /Z-DIO /Z-CT) | 02 | | |
| Option | Factory Setting (Communication protocol) | None (Communication protocol is not specified.) Specified (Specify communication protocol) | No code 1 | | |
| *1 | Host Communication Protocol | None (Communication protocol is not specified.) RKC Communication MODBUS Communication | No code 1 2 | | |

*1 : If factory setting is not specified, the followings are set as default.

- Host communication protocol : RKC Communication.

● EtherCAT Communication Converter : COM-ME-3

| Specifications | | Model and Suffix Code | | | |
|----------------|----------------------|-----------------------------------|----|-----------|--|
| | | COM-ME | | -3 5 * 02 | |
| | Network | EtherCAT | 3 | | |
| | Host communication | RS-485 | 5 | | |
| | Supported Controller | SRZ(Z-TIO-A/Z-TIO-B, Z-DIO, Z-CT) | 02 | | |

● Ethernet MAPMAN Communication Converter : COM-ME-6

| Specifications | | Model and Suffix Code | | | |
|----------------|---|--|-----------------------------|-----------|--------|
| | | COM-ME | | Mandatory | Option |
| Mandatory | Network | Ethernet[Ethernet MAPMAN] | 6 | | |
| | Host communication | RS-485 | 5 | | |
| | Supported Controller | SRZ | 02 | | |
| Option | Factory Setting (Communication protocol) | None (Communication protocol is not specified.) Specified (Specify communication protocol) | No code 1 | | |
| | Host communication protocol | None (Communication protocol is not specified.) RKC Communication MODBUS Communication | No code 1 2 | | |
| | Network communication protocol | None (Communication protocol is not specified.) MAPMAN (MITSUBISHI PLC: QnA-compatible 3E fame/SLMP ASCII) MAPMAN (MITSUBISHI PLC: QnA-compatible 3E fame/SLMP binary) | No code 5 6 | | |
| *1 | The number of the correspondence channels | None (Number of channels is not specified.) 16 channels 32 channels 48 channels 64 channels | No code A B C D | | |

*1 : If factory setting is not specified, the followings are set as default.

- Host communication protocol : RKC Communication.

- Network communication protocol : MAPMAN (MITSUBISHI PLC: QnA-compatible 3E fame /SLMP binary).

- Supported number of channels : 64 channels.

(equivalent to code "/116D")

● MECHATROLINK communication converter (COM-MY)

| Specifications | | Model and Suffix Code | | | |
|-------------------------|--------------------------------------|-----------------------|---|------------|---|
| | | COM - M | | Y - □ * 02 | |
| Type | MECHATROLINK communication converter | | | | |
| Host communication type | RS-422A | | 4 | | 5 |
| Available controller | SRZ (Z-TIO-A/B, Z-DIO) | | | 02 | |

● DeviceNet communication converter (COM-JH)

| Specifications | | Model and Suffix Code | | | |
|-------------------------|-----------------------------------|-----------------------|---|------------|--|
| | | COM - J | | H - □ * 02 | |
| Type | DeviceNet communication converter | H | | | |
| Connector for DevineNet | Open connector (Unshielded type) | | N | | |
| Available controller | Micro connector (Shield type) | | 1 | | |
| | SRZ (Z-TIO-A/B, Z-DIO) | | | 02 | |

● Ethernet (Modbus/TCP) communication converter (COM-JL)

| Specifications | | Model Code | | | |
|----------------------|----------------------------------|------------|---|------------|--|
| | | COM - J | | L - □ * 02 | |
| Type | Ethernet communication converter | L | | | |
| Communication type | Modbus/TCP | | 1 | | |
| Available controller | SRZ (Z-TIO-A/B, Z-DIO) | | | 02 | |

● CC-Link communication converter (COM-JC)

| Specifications | | Model Code | | | |
|--------------------------|---------------------------------|------------|--|------------|--|
| | | COM - J | | C * 02 - □ | |
| Type | CC-Link communication converter | C | | | |
| Available controller | SRZ (Z-TIO-A/B, Z-DIO) | | | 02 | |
| RUN/STOP logic selection | 0 : RUN, 1 : STOP | | | 1 | |
| | 0 : STOP, 1 : RUN | | | 2 | |

● USB communication converter (COM-KG)

| Specifications | | Model Code | | | |
|----------------------------|---------------------------------|------------|--|-----|--|
| | | COM - KG - | | □ N | |
| Loader communication cable | None | | | 1 | |
| | With loader communication cable | | | N | |



- Before operating this product, read the instruction manual carefully to avoid incorrect operation.
- This product is intended for use with industrial machines, test and measuring equipment. It is not designed for use with medical equipment.
- If it is possible that an accident may occur as a result of the failure of the product or some other abnormality, an appropriate independent protection device must be installed.

Caution for the export trade

All transactions must comply with laws, regulations, and treaties.

Caution for imitated products

As products imitating our product now appear on the market, be careful that you don't purchase these imitated products. We will not warrant such products nor bear the responsibility for any damage and/or accident caused by their use.

RKC **RKC INSTRUMENT INC.**
(RIKA KOGYO CO.,LTD)

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